# Package 'bayestestR'

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Type Package

```
Title Understand and Describe Bayesian Models and Posterior
      Distributions
Version 0.15.2
Maintainer Dominique Makowski <dom.makowski@gmail.com>
Description Provides utilities to describe posterior
      distributions and Bayesian models. It includes point-estimates such as
      Maximum A Posteriori (MAP), measures of dispersion (Highest Density
      Interval - HDI; Kruschke, 2015 < doi:10.1016/C2012-0-00477-2>) and
      indices used for null-hypothesis testing (such as ROPE percentage, pd
      and Bayes factors). References: Makowski et al. (2021) <doi:10.21105/joss.01541>.
Depends R (>= 3.6)
Imports insight (>= 1.0.1), datawizard (>= 1.0.0), graphics, methods,
      stats, utils
Suggests BayesFactor (>= 0.9.12-4.4), bayesQR, bayesplot, betareg, BH,
      blavaan, bridgesampling, brms, collapse, curl, effectsize,
      emmeans, gamm4, ggdist, ggplot2, glmmTMB, httr2, KernSmooth,
      knitr, lavaan, lme4, logspline (>= 2.1.21), marginaleffects (>=
      0.24.0), MASS, mclust, mediation, modelbased, ordbetareg,
      parameters, patchwork, performance, quadprog, posterior,
      RcppEigen, rmarkdown, rstan, rstanarm, see (\geq 0.8.5),
      testthat, tweedie, withr
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2 Contents

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area\_under\_curve

Area under the Curve (AUC)

# Description

**Index** 

Based on the DescTools AUC function. It can calculate the area under the curve with a naive algorithm or a more elaborated spline approach. The curve must be given by vectors of xy-coordinates. This function can handle unsorted x values (by sorting x) and ties for the x values (by ignoring duplicates).

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```
area_under_curve(x, y, method = c("trapezoid", "step", "spline"), ...)
auc(x, y, method = c("trapezoid", "step", "spline"), ...)
```

# **Arguments**

Vector of x values. Χ Vector of y values. У

method

Method to compute the Area Under the Curve (AUC). Can be "trapezoid" (default), "step" or "spline". If "trapezoid", the curve is formed by connecting all points by a direct line (composite trapezoid rule). If "step" is chosen then a stepwise connection of two points is used. For calculating the area under a spline interpolation the splinefun function is used in combination with integrate.

Arguments passed to or from other methods. . . .

# See Also

DescTools

# **Examples**

```
library(bayestestR)
posterior <- distribution_normal(1000)</pre>
dens <- estimate_density(posterior)</pre>
dens <- dens[densx > 0, ]
x \leftarrow dens$x
y <- dens$y
area_under_curve(x, y, method = "trapezoid")
area_under_curve(x, y, method = "step")
area_under_curve(x, y, method = "spline")
```

as.data.frame.density Coerce to a Data Frame

# Description

Coerce to a Data Frame

#### Usage

```
## S3 method for class 'density'
as.data.frame(x, ...)
```

# **Arguments**

any R object. Х

additional arguments to be passed to or from methods.

```
as.numeric.map_estimate
```

Convert to Numeric

# **Description**

Convert to Numeric

# Usage

```
## S3 method for class 'map_estimate'
as.numeric(x, ...)
## S3 method for class 'p_direction'
as.numeric(x, ...)
## S3 method for class 'p_map'
as.numeric(x, ...)
## S3 method for class 'p_significance'
as.numeric(x, ...)
```

#### **Arguments**

x object to be coerced or tested.

... further arguments passed to or from other methods.

bayesfactor

Bayes Factors (BF)

# **Description**

This function compte the Bayes factors (BFs) that are appropriate to the input. For vectors or single models, it will compute BFs for single parameters, or is hypothesis is specified, BFs for restricted models. For multiple models, it will return the BF corresponding to comparison between models and if a model comparison is passed, it will compute the inclusion BF.

For a complete overview of these functions, read the Bayes factor vignette.

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# Usage

```
bayesfactor(
    ...,
    prior = NULL,
    direction = "two-sided",
    null = 0,
    hypothesis = NULL,
    effects = c("fixed", "random", "all"),
    verbose = TRUE,
    denominator = 1,
    match_models = FALSE,
    prior_odds = NULL
)
```

# **Arguments**

	A numeric vector, model object(s), or the output from $bayesfactor\_models$ .
prior	An object representing a prior distribution (see 'Details').
direction	Test type (see 'Details'). One of 0, "two-sided" (default, two tailed), -1, "left" (left tailed) or 1, "right" (right tailed).
null	Value of the null, either a scalar (for point-null) or a range (for a interval-null).
hypothesis	A character vector specifying the restrictions as logical conditions (see examples below).
effects	Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.
verbose	Toggle off warnings.
denominator	Either an integer indicating which of the models to use as the denominator, or a model to be used as a denominator. Ignored for BFBayesFactor.
match_models	See details.

# Value

prior\_odds

Some type of Bayes factor, depending on the input. See bayes factor\_parameters(), bayes factor\_models() or bayes factor\_inclusion().

Optional vector of prior odds for the models. See BayesFactor::priorOdds<-.

# Note

There is also a plot()-method implemented in the see-package.

# Examples

```
## Not run:
library(bayestestR)
prior <- distribution_normal(1000, mean = 0, sd = 1)</pre>
```

bayesfactor\_inclusion 7

```
posterior <- distribution_normal(1000, mean = 0.5, sd = 0.3)

bayesfactor(posterior, prior = prior, verbose = FALSE)

# rstanarm models
# -------
model <- suppressWarnings(rstanarm::stan_lmer(extra ~ group + (1 | ID), data = sleep))
bayesfactor(model, verbose = FALSE)

# Frequentist models
# -------
m0 <- lm(extra ~ 1, data = sleep)
m1 <- lm(extra ~ group, data = sleep)
m2 <- lm(extra ~ group + ID, data = sleep)
comparison <- bayesfactor(m0, m1, m2)
comparison

bayesfactor(comparison)

## End(Not run)</pre>
```

bayesfactor\_inclusion Inclusion Bayes Factors for testing predictors across Bayesian models

# **Description**

The bf\_\* function is an alias of the main function.

For more info, see the Bayes factors vignette.

# Usage

```
bayesfactor_inclusion(models, match_models = FALSE, prior_odds = NULL, ...)
bf_inclusion(models, match_models = FALSE, prior_odds = NULL, ...)
```

# **Arguments**

```
models An object of class bayesfactor_models() or BFBayesFactor.

match_models See details.

prior_odds Optional vector of prior odds for the models. See BayesFactor::priorOdds<-.

Arguments passed to or from other methods.
```

#### **Details**

Inclusion Bayes factors answer the question: Are the observed data more probable under models with a particular effect, than they are under models without that particular effect? In other words, on average - are models with effect X more likely to have produced the observed data than models without effect X?

**Match Models:** If match\_models=FALSE (default), Inclusion BFs are computed by comparing all models with a term against all models without that term. If TRUE, comparison is restricted to models that (1) do not include any interactions with the term of interest; (2) for interaction terms, averaging is done only across models that contains the main effect terms from which the interaction term is comprised.

#### Value

a data frame containing the prior and posterior probabilities, and log(BF) for each effect (Use as.numeric() to extract the non-log Bayes factors; see examples).

#### **Interpreting Bayes Factors**

A Bayes factor greater than 1 can be interpreted as evidence against the null, at which one convention is that a Bayes factor greater than 3 can be considered as "substantial" evidence against the null (and vice versa, a Bayes factor smaller than 1/3 indicates substantial evidence in favor of the null-model) (*Wetzels et al. 2011*).

#### Note

Random effects in the 1mer style are converted to interaction terms: i.e., (X|G) will become the terms 1:G and X:G.

#### Author(s)

Mattan S. Ben-Shachar

#### References

- Hinne, M., Gronau, Q. F., van den Bergh, D., and Wagenmakers, E. (2019, March 25). A
  conceptual introduction to Bayesian Model Averaging. doi:10.31234/osf.io/wgb64
- Clyde, M. A., Ghosh, J., & Littman, M. L. (2011). Bayesian adaptive sampling for variable selection and model averaging. Journal of Computational and Graphical Statistics, 20(1), 80-101.
- Mathot, S. (2017). Bayes like a Baws: Interpreting Bayesian Repeated Measures in JASP. Blog post.

#### See Also

weighted\_posteriors() for Bayesian parameter averaging.

# **Examples**

bayesfactor\_models

Bayes Factors (BF) for model comparison

# **Description**

This function computes or extracts Bayes factors from fitted models.

The bf\_\* function is an alias of the main function.

```
bayesfactor_models(..., denominator = 1, verbose = TRUE)

bf_models(..., denominator = 1, verbose = TRUE)

## Default S3 method:
bayesfactor_models(..., denominator = 1, verbose = TRUE)

## S3 method for class 'bayesfactor_models'
update(object, subset = NULL, reference = NULL, ...)

## S3 method for class 'bayesfactor_models'
as.matrix(x, ...)
```

#### **Arguments**

.. Fitted models (see details), all fit on the same data, or a single BFBayesFactor

object (see 'Details'). Ignored in as.matrix(), update(). If the following named arguments are present, they are passed to insight::get\_loglikelihood()

(see details):

• estimator (defaults to "ML")

• check\_response (defaults to FALSE)

denominator Either an integer indicating which of the models to use as the denominator, or a

model to be used as a denominator. Ignored for BFBayesFactor.

verbose Toggle off warnings.

object, x A bayesfactor\_models() object.

subset Vector of model indices to keep or remove.

reference Index of model to reference to, or "top" to reference to the best model, or

"bottom" to reference to the worst model.

#### **Details**

If the passed models are supported by **insight** the DV of all models will be tested for equality (else this is assumed to be true), and the models' terms will be extracted (allowing for follow-up analysis with bayesfactor\_inclusion).

- For brmsfit or stanneg models, Bayes factors are computed using the bridgesampling package.
  - brmsfit models must have been fitted with save\_pars = save\_pars(all = TRUE).
  - stanreg models must have been fitted with a defined diagnostic\_file.
- For BFBayesFactor, bayesfactor\_models() is mostly a wraparound BayesFactor::extractBF().
- For all other model types, Bayes factors are computed using the BIC approximation. Note that BICs are extracted from using <a href="mailto:insight::get\_loglikelihood">insight::get\_loglikelihood</a>, see documentation there for options for dealing with transformed responses and REML estimation.

In order to correctly and precisely estimate Bayes factors, a rule of thumb are the 4 P's: **Proper Priors** and **Plentiful Posteriors**. How many? The number of posterior samples needed for testing is substantially larger than for estimation (the default of 4000 samples may not be enough in many cases). A conservative rule of thumb is to obtain 10 times more samples than would be required for estimation (*Gronau, Singmann, & Wagenmakers, 2017*). If less than 40,000 samples are detected, bayesfactor\_models() gives a warning.

See also the Bayes factors vignette.

# Value

A data frame containing the models' formulas (reconstructed fixed and random effects) and their log(BF)s (Use as.numeric() to extract the non-log Bayes factors; see examples), that prints nicely.

#### **Interpreting Bayes Factors**

A Bayes factor greater than 1 can be interpreted as evidence against the null, at which one convention is that a Bayes factor greater than 3 can be considered as "substantial" evidence against the null (and vice versa, a Bayes factor smaller than 1/3 indicates substantial evidence in favor of the null-model) (Wetzels et al. 2011).

#### Note

There is also a plot()-method implemented in the see-package.

# Author(s)

Mattan S. Ben-Shachar

#### References

- Gronau, Q. F., Singmann, H., & Wagenmakers, E. J. (2017). Bridgesampling: An R package for estimating normalizing constants. arXiv preprint arXiv:1710.08162.
- Kass, R. E., and Raftery, A. E. (1995). Bayes Factors. Journal of the American Statistical Association, 90(430), 773-795.
- Robert, C. P. (2016). The expected demise of the Bayes factor. Journal of Mathematical Psychology, 72, 33–37.
- Wagenmakers, E. J. (2007). A practical solution to the pervasive problems of p values. Psychonomic bulletin & review, 14(5), 779-804.
- Wetzels, R., Matzke, D., Lee, M. D., Rouder, J. N., Iverson, G. J., and Wagenmakers, E.-J. (2011). Statistical Evidence in Experimental Psychology: An Empirical Comparison Using 855 t Tests. Perspectives on Psychological Science, 6(3), 291–298. doi:10.1177/1745691611406923

# **Examples**

```
# With lmerMod objects:
lmer1 <- lme4::lmer(Sepal.Length ~ Petal.Length + (1 | Species), data = iris)</pre>
lmer2 <- lme4::lmer(Sepal.Length ~ Petal.Length + (Petal.Length | Species), data = iris)</pre>
lmer3 <- lme4::lmer(</pre>
  Sepal.Length ~ Petal.Length + (Petal.Length | Species) + (1 | Petal.Width),
  data = iris
bayesfactor_models(lmer1, lmer2, lmer3,
  denominator = 1,
  estimator = "REML"
# rstanarm models
# (note that a unique diagnostic_file MUST be specified in order to work)
stan_m0 <- suppressWarnings(rstanarm::stan_glm(Sepal.Length ~ 1,</pre>
  data = iris,
  family = gaussian(),
  diagnostic_file = file.path(tempdir(), "df0.csv")
))
stan_m1 <- suppressWarnings(rstanarm::stan_glm(Sepal.Length ~ Species,</pre>
  data = iris,
  family = gaussian(),
  diagnostic_file = file.path(tempdir(), "df1.csv")
stan_m2 <- suppressWarnings(rstanarm::stan_glm(Sepal.Length ~ Species + Petal.Length,</pre>
  data = iris,
  family = gaussian(),
  diagnostic_file = file.path(tempdir(), "df2.csv")
bayesfactor_models(stan_m1, stan_m2, denominator = stan_m0, verbose = FALSE)
# brms models
# (note the save_pars MUST be set to save_pars(all = TRUE) in order to work)
brm1 <- brms::brm(Sepal.Length ~ 1, data = iris, save_pars = save_pars(all = TRUE))</pre>
brm2 <- brms::brm(Sepal.Length ~ Species, data = iris, save_pars = save_pars(all = TRUE))</pre>
brm3 <- brms::brm(</pre>
  Sepal.Length ~ Species + Petal.Length,
  data = iris,
  save_pars = save_pars(all = TRUE)
)
bayesfactor_models(brm1, brm2, brm3, denominator = 1, verbose = FALSE)
# BayesFactor
# -----
data(puzzles)
BF <- BayesFactor::anovaBF(RT ~ shape * color + ID,
  data = puzzles,
```

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```
whichRandom = "ID", progress = FALSE
)
BF
bayesfactor_models(BF) # basically the same
```

bayesfactor\_parameters

Bayes Factors (BF) for a Single Parameter

# **Description**

This method computes Bayes factors against the null (either a point or an interval), based on prior and posterior samples of a single parameter. This Bayes factor indicates the degree by which the mass of the posterior distribution has shifted further away from or closer to the null value(s) (relative to the prior distribution), thus indicating if the null value has become less or more likely given the observed data.

When the null is an interval, the Bayes factor is computed by comparing the prior and posterior odds of the parameter falling within or outside the null interval (Morey & Rouder, 2011; Liao et al., 2020); When the null is a point, a Savage-Dickey density ratio is computed, which is also an approximation of a Bayes factor comparing the marginal likelihoods of the model against a model in which the tested parameter has been restricted to the point null (Wagenmakers et al., 2010; Heck, 2019).

Note that the logspline package is used for estimating densities and probabilities, and must be installed for the function to work.

bayesfactor\_pointnull() and bayesfactor\_rope() are wrappers around bayesfactor\_parameters with different defaults for the null to be tested against (a point and a range, respectively). Aliases of the main functions are prefixed with bf\_\*, like bf\_parameters() or bf\_pointnull().

For more info, in particular on specifying correct priors for factors with more than 2 levels, see the Bayes factors vignette.

```
bayesfactor_parameters(
  posterior,
  prior = NULL,
  direction = "two-sided",
  null = 0,
   ...,
  verbose = TRUE
)
```

```
bayesfactor_pointnull(
  posterior,
 prior = NULL,
 direction = "two-sided",
 null = 0,
 verbose = TRUE
)
bayesfactor_rope(
 posterior,
 prior = NULL,
 direction = "two-sided",
 null = rope_range(posterior, verbose = FALSE),
  verbose = TRUE
)
bf_parameters(
  posterior,
 prior = NULL,
 direction = "two-sided",
 null = 0,
  . . . ,
 verbose = TRUE
)
bf_pointnull(
  posterior,
 prior = NULL,
 direction = "two-sided",
 null = 0,
  ...,
  verbose = TRUE
)
bf_rope(
 posterior,
 prior = NULL,
 direction = "two-sided",
 null = rope_range(posterior, verbose = FALSE),
  verbose = TRUE
)
## S3 method for class 'numeric'
bayesfactor_parameters(
 posterior,
```

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```
prior = NULL,
  direction = "two-sided",
  null = 0,
  . . . ,
  verbose = TRUE
)
## S3 method for class 'stanreg'
bayesfactor_parameters(
 posterior,
 prior = NULL,
  direction = "two-sided",
  null = 0,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "location", "smooth_terms", "sigma", "zi",
    "zero_inflated", "all"),
  parameters = NULL,
  . . . ,
  verbose = TRUE
## S3 method for class 'brmsfit'
bayesfactor_parameters(
 posterior,
  prior = NULL,
  direction = "two-sided",
  null = 0,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "location", "smooth_terms", "sigma", "zi",
    "zero_inflated", "all"),
  parameters = NULL,
  verbose = TRUE
)
## S3 method for class 'blavaan'
bayesfactor_parameters(
 posterior,
 prior = NULL,
 direction = "two-sided",
 null = 0,
  . . . ,
  verbose = TRUE
)
## S3 method for class 'data.frame'
bayesfactor_parameters(
  posterior,
```

```
prior = NULL,
  direction = "two-sided",
  null = 0,
  rvar_col = NULL,
    ...,
  verbose = TRUE
)
```

# **Arguments**

posterior	A numerical vector, stanreg / brmsfit object, emmGrid or a data frame - representing a posterior distribution(s) from (see 'Details').
prior	An object representing a prior distribution (see 'Details').
direction	Test type (see 'Details'). One of 0, "two-sided" (default, two tailed), -1, "left" (left tailed) or 1, "right" (right tailed).
null	Value of the null, either a scalar (for point-null) or a range (for a interval-null).
	Arguments passed to and from other methods. (Can be used to pass arguments to internal logspline::logspline().)
verbose	Toggle off warnings.
effects	Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.
component	Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to <b>brms</b> -models.
parameters	Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like 1p or prior_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output.
rvar_col	A single character - the name of an rvar column in the data frame to be processed. See example in p_direction().

# **Details**

This method is used to compute Bayes factors based on prior and posterior distributions.

One-sided & Dividing Tests (setting an order restriction): One sided tests (controlled by direction) are conducted by restricting the prior and posterior of the non-null values (the "alternative") to one side of the null only (*Morey & Wagenmakers*, 2014). For example, if we have a prior hypothesis that the parameter should be positive, the alternative will be restricted to the region to the right of the null (point or interval). For example, for a Bayes factor comparing the "null" of 0-0.1 to the alternative >0.1, we would set bayesfactor\_parameters(null = c(0, 0.1), direction = ">").

It is also possible to compute a Bayes factor for **dividing** hypotheses - that is, for a null and alternative that are complementary, opposing one-sided hypotheses (*Morey & Wagenmakers*, 2014). For example, for a Bayes factor comparing the "null" of <0 to the alternative >0, we would set bayesfactor\_parameters(null = c(-Inf, 0)).

#### Value

A data frame containing the (log) Bayes factor representing evidence *against* the null (Use as . numeric() to extract the non-log Bayes factors; see examples).

# Setting the correct prior

For the computation of Bayes factors, the model priors must be proper priors (at the very least they should be *not flat*, and it is preferable that they be *informative*); As the priors for the alternative get wider, the likelihood of the null value(s) increases, to the extreme that for completely flat priors the null is infinitely more favorable than the alternative (this is called *the Jeffreys-Lindley-Bartlett paradox*). Thus, you should only ever try (or want) to compute a Bayes factor when you have an informed prior.

(Note that by default, brms::brm() uses flat priors for fixed-effects; See example below.)

It is important to provide the correct prior for meaningful results, to match the posterior-type input:

- A numeric vector prior should also be a *numeric vector*, representing the prior-estimate.
- A data frame prior should also be a *data frame*, representing the prior-estimates, in matching column order.
  - If rvar\_col is specified, prior should be the name of an rvar column that represents the prior-estimates.
- Supported Bayesian model (stanreg, brmsfit, etc.)
  - prior should be a model an equivalent model with MCMC samples from the priors only.
     See unupdate().
  - If prior is set to NULL, unupdate() is called internally (not supported for brmsfit\_multiple model).
- Output from a {marginaleffects} function prior should also be an equivalent output from a {marginaleffects} function based on a prior-model (See unupdate()).
- Output from an {emmeans} function
  - prior should also be an equivalent output from an {emmeans} function based on a prior-model (See unupdate()).
  - prior can also be the original (posterior) model, in which case the function will try to "unupdate" the estimates (not supported if the estimates have undergone any transformations – "log", "response", etc. – or any regriding).

# **Interpreting Bayes Factors**

A Bayes factor greater than 1 can be interpreted as evidence against the null, at which one convention is that a Bayes factor greater than 3 can be considered as "substantial" evidence against the null (and vice versa, a Bayes factor smaller than 1/3 indicates substantial evidence in favor of the null-model) (Wetzels et al. 2011).

# Note

There is also a plot()-method implemented in the see-package.

#### Author(s)

Mattan S. Ben-Shachar

#### References

- Wagenmakers, E. J., Lodewyckx, T., Kuriyal, H., and Grasman, R. (2010). Bayesian hypothesis testing for psychologists: A tutorial on the Savage-Dickey method. Cognitive psychology, 60(3), 158-189.
- Heck, D. W. (2019). A caveat on the Savage–Dickey density ratio: The case of computing Bayes factors for regression parameters. British Journal of Mathematical and Statistical Psychology, 72(2), 316-333.
- Morey, R. D., & Wagenmakers, E. J. (2014). Simple relation between Bayesian order-restricted and point-null hypothesis tests. Statistics & Probability Letters, 92, 121-124.
- Morey, R. D., & Rouder, J. N. (2011). Bayes factor approaches for testing interval null hypotheses. Psychological methods, 16(4), 406.
- Liao, J. G., Midya, V., & Berg, A. (2020). Connecting and contrasting the Bayes factor and a modified ROPE procedure for testing interval null hypotheses. The American Statistician, 1-19.
- Wetzels, R., Matzke, D., Lee, M. D., Rouder, J. N., Iverson, G. J., and Wagenmakers, E.-J. (2011). Statistical Evidence in Experimental Psychology: An Empirical Comparison Using 855 t Tests. Perspectives on Psychological Science, 6(3), 291–298. doi:10.1177/1745691611406923

# **Examples**

```
library(bayestestR)
prior <- distribution_normal(1000, mean = 0, sd = 1)</pre>
posterior <- distribution_normal(1000, mean = .5, sd = .3)</pre>
(BF_pars <- bayesfactor_parameters(posterior, prior, verbose = FALSE))
as.numeric(BF_pars)
# rstanarm models
contrasts(sleep$group) <- contr.equalprior_pairs # see vingette</pre>
stan_model <- suppressWarnings(stan_lmer(</pre>
 extra \sim group + (1 | ID),
 data = sleep,
 refresh = 0
))
bayesfactor_parameters(stan_model, verbose = FALSE)
bayesfactor_parameters(stan_model, null = rope_range(stan_model))
# emmGrid objects
group_diff <- pairs(emmeans(stan_model, ~group, data = sleep))</pre>
bayesfactor_parameters(group_diff, prior = stan_model, verbose = FALSE)
```

```
# Or
# group_diff_prior <- pairs(emmeans(unupdate(stan_model), ~group))</pre>
# bayesfactor_parameters(group_diff, prior = group_diff_prior, verbose = FALSE)
# brms models
# -----
## Not run:
contrasts(sleep$group) <- contr.equalprior_pairs # see vingette</pre>
my_custom_priors <-</pre>
  set_prior("student_t(3, 0, 1)", class = "b") +
  set_prior("student_t(3, 0, 1)", class = "sd", group = "ID")
brms_model <- suppressWarnings(brm(extra ~ group + (1 | ID),</pre>
  data = sleep,
  prior = my_custom_priors,
  refresh = 0
))
bayesfactor_parameters(brms_model, verbose = FALSE)
## End(Not run)
```

bayesfactor\_restricted

Bayes Factors (BF) for Order Restricted Models

# Description

This method computes Bayes factors for comparing a model with an order restrictions on its parameters with the fully unrestricted model. *Note that this method should only be used for confirmatory analyses*.

The bf\_\* function is an alias of the main function.

For more info, in particular on specifying correct priors for factors with more than 2 levels, see the Bayes factors vignette.

```
bayesfactor_restricted(posterior, ...)
bf_restricted(posterior, ...)
## S3 method for class 'stanreg'
bayesfactor_restricted(
   posterior,
   hypothesis,
```

```
prior = NULL,
  verbose = TRUE,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
)
## S3 method for class 'brmsfit'
bayesfactor_restricted(
  posterior,
  hypothesis,
  prior = NULL,
  verbose = TRUE,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
)
## S3 method for class 'blavaan'
bayesfactor_restricted(
 posterior,
 hypothesis,
 prior = NULL,
  verbose = TRUE,
)
## S3 method for class 'emmGrid'
bayesfactor_restricted(
 posterior,
 hypothesis,
 prior = NULL,
  verbose = TRUE,
)
## S3 method for class 'data.frame'
bayesfactor_restricted(
 posterior,
 hypothesis,
 prior = NULL,
 rvar_col = NULL,
)
## S3 method for class 'bayesfactor_restricted'
as.logical(x, which = c("posterior", "prior"), ...)
```

#### **Arguments**

posterior A stanreg / brmsfit object, emmGrid or a data frame - representing a posterior

distribution(s) from (see Details).

... Currently not used.

hypothesis A character vector specifying the restrictions as logical conditions (see examples

below)

prior An object representing a prior distribution (see Details).

verbose Toggle off warnings.

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

x An object of class bayesfactor\_restricted

which Should the logical matrix be of the posterior or prior distribution(s)?

#### **Details**

This method is used to compute Bayes factors for order-restricted models vs un-restricted models by setting an order restriction on the prior and posterior distributions (*Morey & Wagenmakers*, 2013).

(Though it is possible to use bayesfactor\_restricted() to test interval restrictions, it is more suitable for testing order restrictions; see examples).

# Value

A data frame containing the (log) Bayes factor representing evidence *against* the un-restricted model (Use as.numeric() to extract the non-log Bayes factors; see examples). (A bool\_results attribute contains the results for each sample, indicating if they are included or not in the hypothesized restriction.)

# Setting the correct prior

For the computation of Bayes factors, the model priors must be proper priors (at the very least they should be *not flat*, and it is preferable that they be *informative*); As the priors for the alternative get wider, the likelihood of the null value(s) increases, to the extreme that for completely flat priors the null is infinitely more favorable than the alternative (this is called *the Jeffreys-Lindley-Bartlett paradox*). Thus, you should only ever try (or want) to compute a Bayes factor when you have an informed prior.

(Note that by default, brms::brm() uses flat priors for fixed-effects; See example below.)

It is important to provide the correct prior for meaningful results, to match the posterior-type input:

• A numeric vector - prior should also be a *numeric vector*, representing the prior-estimate.

- A data frame prior should also be a *data frame*, representing the prior-estimates, in matching column order.
  - If rvar\_col is specified, prior should be *the name of an* rvar *column* that represents the prior-estimates.
- Supported Bayesian model (stanreg, brmsfit, etc.)
  - prior should be a model an equivalent model with MCMC samples from the priors only.
     See unupdate().
  - If prior is set to NULL, unupdate() is called internally (not supported for brmsfit\_multiple model).
- Output from a {marginaleffects} function prior should also be an equivalent output from a {marginaleffects} function based on a prior-model (See unupdate()).
- Output from an {emmeans} function
  - prior should also be an equivalent output from an {emmeans} function based on a prior-model (See unupdate()).
  - prior can also be the original (posterior) model, in which case the function will try to "unupdate" the estimates (not supported if the estimates have undergone any transformations – "log", "response", etc. – or any regriding).

# **Interpreting Bayes Factors**

A Bayes factor greater than 1 can be interpreted as evidence against the null, at which one convention is that a Bayes factor greater than 3 can be considered as "substantial" evidence against the null (and vice versa, a Bayes factor smaller than 1/3 indicates substantial evidence in favor of the null-model) (Wetzels et al. 2011).

#### References

- Morey, R. D., & Wagenmakers, E. J. (2014). Simple relation between Bayesian order-restricted and point-null hypothesis tests. Statistics & Probability Letters, 92, 121-124.
- Morey, R. D., & Rouder, J. N. (2011). Bayes factor approaches for testing interval null hypotheses. Psychological methods, 16(4), 406.
- Morey, R. D. (Jan, 2015). Multiple Comparisons with BayesFactor, Part 2 order restrictions. Retrieved from https://richarddmorey.org/category/order-restrictions/.

# **Examples**

```
set.seed(444)
library(bayestestR)
prior <- data.frame(
   A = rnorm(500),
   B = rnorm(500),
   C = rnorm(500)
)

posterior <- data.frame(
   A = rnorm(500, .4, 0.7),</pre>
```

```
B = rnorm(500, -.2, 0.4),
 C = rnorm(500, 0, 0.5)
)
hyps <- c(
  "A > B & B > C",
  "A > B & A > C",
  "C > A"
)
(b <- bayesfactor_restricted(posterior, hypothesis = hyps, prior = prior))</pre>
bool <- as.logical(b, which = "posterior")</pre>
head(bool)
see::plots(
  plot(estimate_density(posterior)),
  # distribution **conditional** on the restrictions
  plot(estimate_density(posterior[bool[, hyps[1]], ])) + ggplot2::ggtitle(hyps[1]),
  plot(estimate_density(posterior[bool[, hyps[2]], ])) + ggplot2::ggtitle(hyps[2]),
  plot(estimate_density(posterior[bool[, hyps[3]], ])) + ggplot2::ggtitle(hyps[3]),
  guides = "collect"
)
# rstanarm models
# -----
data("mtcars")
fit_stan <- rstanarm::stan_glm(mpg ~ wt + cyl + am,</pre>
  data = mtcars, refresh = 0
)
hyps <- c(
  "am > 0 & cyl < 0",
  "cyl < 0",
  "wt - cyl > 0"
bayesfactor_restricted(fit_stan, hypothesis = hyps)
# emmGrid objects
# replicating http://bayesfactor.blogspot.com/2015/01/multiple-comparisons-with-bayesfactor-2.html
data("disgust")
contrasts(disgust$condition) <- contr.equalprior_pairs # see vignette</pre>
fit_model <- rstanarm::stan_glm(score ~ condition, data = disgust, family = gaussian())</pre>
```

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bci

Bias Corrected and Accelerated Interval (BCa)

# **Description**

Compute the Bias Corrected and Accelerated Interval (BCa) of posterior distributions.

```
bci(x, ...)
bcai(x, ...)
## S3 method for class 'numeric'
bci(x, ci = 0.95, verbose = TRUE, ...)
## S3 method for class 'data.frame'
bci(x, ci = 0.95, rvar\_col = NULL, verbose = TRUE, ...)
## S3 method for class 'MCMCglmm'
bci(x, ci = 0.95, verbose = TRUE, ...)
## S3 method for class 'sim.merMod'
bci(
  Х,
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'sim'
bci(x, ci = 0.95, parameters = NULL, verbose = TRUE, ...)
```

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```
## S3 method for class 'emmGrid'
bci(x, ci = 0.95, verbose = TRUE, ...)
## S3 method for class 'slopes'
bci(x, ci = 0.95, verbose = TRUE, ...)
## S3 method for class 'stanreg'
bci(
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'brmsfit'
bci(
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'BFBayesFactor'
bci(x, ci = 0.95, verbose = TRUE, ...)
## S3 method for class 'get_predicted'
bci(x, ci = 0.95, use_iterations = FALSE, verbose = TRUE, ...)
```

# **Arguments**

v Vector representing a posterior distribution, or a data frame of such vectors. Can also be a Bayesian model. bayestestR supports a wide range of models (see, for example, methods("hdi")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly resemble the arguments of the .numeric or .data.framemethods.

... Currently not used.

value or vector of probability of the (credible) interval - CI (between 0 and 1) to be estimated. Default to .95 (95%).

verbose Toggle off warnings.

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rvar\_col A single character - the name of an rvar column in the data frame to be processed. See example in p\_direction(). effects Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated. Regular expression pattern that describes the parameters that should be returned. parameters Meta-parameters (like lp\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output. Should results for all parameters, parameters for the conditional model or the component zero-inflated part of the model be returned? May be abbreviated. Only applies to brms-models.

use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()), the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

#### **Details**

Unlike equal-tailed intervals (see eti()) that typically exclude 2.5% from each tail of the distribution and always include the median, the HDI is not equal-tailed and therefore always includes the mode(s) of posterior distributions. While this can be useful to better represent the credibility mass of a distribution, the HDI also has some limitations. See spi() for details.

The 95% or 89% Credible Intervals (CI) are two reasonable ranges to characterize the uncertainty related to the estimation (see here for a discussion about the differences between these two values).

The 89% intervals (ci = 0.89) are deemed to be more stable than, for instance, 95% intervals (Kruschke, 2014). An effective sample size of at least 10.000 is recommended if one wants to estimate 95% intervals with high precision (Kruschke, 2014, p. 183ff). Unfortunately, the default number of posterior samples for most Bayes packages (e.g., rstanarm or brms) is only 4.000 (thus, you might want to increase it when fitting your model). Moreover, 89 indicates the arbitrariness of interval limits - its only remarkable property is being the highest prime number that does not exceed the already unstable 95% threshold (McElreath, 2015).

However, 95% has some advantages too. For instance, it shares (in the case of a normal posterior distribution) an intuitive relationship with the standard deviation and it conveys a more accurate image of the (artificial) bounds of the distribution. Also, because it is wider, it makes analyses more conservative (i.e., the probability of covering 0 is larger for the 95% CI than for lower ranges such as 89%), which is a good thing in the context of the reproducibility crisis.

A 95% equal-tailed interval (ETI) has 2.5% of the distribution on either side of its limits. It indicates the 2.5th percentile and the 97.5h percentile. In symmetric distributions, the two methods of computing credible intervals, the ETI and the HDI, return similar results.

This is not the case for skewed distributions. Indeed, it is possible that parameter values in the ETI have lower credibility (are less probable) than parameter values outside the ETI. This property seems undesirable as a summary of the credible values in a distribution.

On the other hand, the ETI range does change when transformations are applied to the distribution (for instance, for a log odds scale to probabilities): the lower and higher bounds of the transformed distribution will correspond to the transformed lower and higher bounds of the original distribution. On the contrary, applying transformations to the distribution will change the resulting HDI.

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# Value

A data frame with following columns:

- Parameter The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- CI The probability of the credible interval.
- CI\_low, CI\_high The lower and upper credible interval limits for the parameters.

#### References

DiCiccio, T. J. and B. Efron. (1996). Bootstrap Confidence Intervals. Statistical Science. 11(3): 189–212. 10.1214/ss/1032280214

#### See Also

```
Other ci: ci(), eti(), hdi(), si(), spi()
```

# Examples

```
posterior <- rnorm(1000)
bci(posterior)
bci(posterior, ci = c(0.80, 0.89, 0.95))</pre>
```

bic\_to\_bf

Convert BIC indices to Bayes Factors via the BIC-approximation method.

# **Description**

The difference between two Bayesian information criterion (BIC) indices of two models can be used to approximate Bayes factors via:

$$BF_{10} = e^{(BIC_0 - BIC_1)/2}$$

#### Usage

```
bic_to_bf(bic, denominator, log = FALSE)
```

# Arguments

bic A vector of BIC values.

denominator The BIC value to use as a denominator (to test against).

log If TRUE, return the log(BF).

# Value

The Bayes Factors corresponding to the BIC values against the denominator.

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#### References

Wagenmakers, E. J. (2007). A practical solution to the pervasive problems of p values. Psychonomic bulletin & review, 14(5), 779-804

# **Examples**

```
bic1 <- BIC(lm(Sepal.Length ~ 1, data = iris))
bic2 <- BIC(lm(Sepal.Length ~ Species, data = iris))
bic3 <- BIC(lm(Sepal.Length ~ Species + Petal.Length, data = iris))
bic4 <- BIC(lm(Sepal.Length ~ Species * Petal.Length, data = iris))
bic_to_bf(c(bic1, bic2, bic3, bic4), denominator = bic1)</pre>
```

check\_prior

Check if Prior is Informative

# **Description**

Performs a simple test to check whether the prior is informative to the posterior. This idea, and the accompanying heuristics, were discussed in *Gelman et al. 2017*.

#### **Usage**

```
check_prior(model, method = "gelman", simulate_priors = TRUE, ...)
```

# **Arguments**

model A stanreg, stanfit, brmsfit, blavaan, or MCMCglmm object.

method Can be "gelman" or "lakeland". For the "gelman" method, if the SD of the

posterior is more than 0.1 times the SD of the prior, then the prior is considered as informative. For the "lakeland" method, the prior is considered as informa-

tive if the posterior falls within the 95% HDI of the prior.

simulate\_priors

Should prior distributions be simulated using simulate\_prior() (default; faster)

or sampled via unupdate() (slower, more accurate).

. . . Currently not used.

#### Value

A data frame with two columns: The parameter names and the quality of the prior (which might be "informative", "uninformative") or "not determinable" if the prior distribution could not be determined).

#### References

Gelman, A., Simpson, D., and Betancourt, M. (2017). The Prior Can Often Only Be Understood in the Context of the Likelihood. Entropy, 19(10), 555. doi:10.3390/e19100555

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# **Examples**

```
library(bayestestR)
model <- rstanarm::stan_glm(mpg ~ wt + am, data = mtcars, chains = 1, refresh = 0)
check_prior(model, method = "gelman")
check_prior(model, method = "lakeland")

# An extreme example where both methods diverge:
model <- rstanarm::stan_glm(mpg ~ wt,
    data = mtcars[1:3, ],
    prior = normal(-3.3, 1, FALSE),
    prior_intercept = normal(0, 1000, FALSE),
    refresh = 0
)
check_prior(model, method = "gelman")
check_prior(model, method = "lakeland")
# can provide visual confirmation to the Lakeland method
plot(si(model, verbose = FALSE))</pre>
```

Confidence/Credible/Compatibility Interval (CI)

Description

ci

Compute Confidence/Credible/Compatibility Intervals (CI) or Support Intervals (SI) for Bayesian and frequentist models. The Documentation is accessible for:

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```
)
   ## S3 method for class 'sim'
   ci(x, ci = 0.95, method = "ETI", parameters = NULL, verbose = TRUE, ...)
   ## S3 method for class 'stanreg'
   ci(
     ci = 0.95,
     method = "ETI",
     effects = c("fixed", "random", "all"),
      component = c("location", "all", "conditional", "smooth_terms", "sigma",
        "distributional", "auxiliary"),
     parameters = NULL,
     verbose = TRUE,
     BF = 1,
   )
   ## S3 method for class 'brmsfit'
   ci(
     х.
     ci = 0.95,
     method = "ETI",
     effects = c("fixed", "random", "all"),
      component = c("conditional", "zi", "zero_inflated", "all"),
     parameters = NULL,
     verbose = TRUE,
     BF = 1,
   )
   ## S3 method for class 'BFBayesFactor'
   ci(x, ci = 0.95, method = "ETI", verbose = TRUE, BF = 1, ...)
   ## S3 method for class 'MCMCglmm'
   ci(x, ci = 0.95, method = "ETI", verbose = TRUE, ...)
Arguments
                    A stanneg or brmsfit model, or a vector representing a posterior distribution.
                    Currently not used.
                    Value or vector of probability of the CI (between 0 and 1) to be estimated. De-
   ci
                    fault to 0.95 (95%).
                    Can be "ETI" (default), "HDI", "BCI", "SPI" or "SI".
   method
   verbose
                    Toggle off warnings.
   BF
                    The amount of support required to be included in the support interval.
```

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rvar_col	A single character - the name of an rvar column in the data frame to be processed. See example in p_direction().
effects	Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.
parameters	Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like lp_ or prior_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output.
component	Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to <b>brms</b> -models.

# **Details**

- · Bayesian models
- Frequentist models

# Value

A data frame with following columns:

- Parameter The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- CI The probability of the credible interval.
- CI\_low, CI\_high The lower and upper credible interval limits for the parameters.

#### Note

When it comes to interpretation, we recommend thinking of the CI in terms of an "uncertainty" or "compatibility" interval, the latter being defined as "Given any value in the interval and the background assumptions, the data should not seem very surprising" (*Gelman & Greenland 2019*).

There is also a plot()-method implemented in the see-package.

#### References

Gelman A, Greenland S. Are confidence intervals better termed "uncertainty intervals"? BMJ 2019;15381. 10.1136/bmj.15381

# See Also

```
Other ci: bci(), eti(), hdi(), si(), spi()
```

# **Examples**

```
library(bayestestR)

posterior <- rnorm(1000)
ci(posterior, method = "ETI")</pre>
```

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```
ci(posterior, method = "HDI")

df <- data.frame(replicate(4, rnorm(100)))
ci(df, method = "ETI", ci = c(0.80, 0.89, 0.95))
ci(df, method = "HDI", ci = c(0.80, 0.89, 0.95))

model <- suppressWarnings(
    stan_glm(mpg ~ wt, data = mtcars, chains = 2, iter = 200, refresh = 0)
)
ci(model, method = "ETI", ci = c(0.80, 0.89))
ci(model, method = "HDI", ci = c(0.80, 0.89))

bf <- ttestBF(x = rnorm(100, 1, 1))
ci(bf, method = "ETI")
ci(bf, method = "HDI")

model <- emtrends(model, ~1, "wt", data = mtcars)
ci(model, method = "ETI")
ci(model, method = "HDI")</pre>
```

contr.equalprior

Contrast Matrices for Equal Marginal Priors in Bayesian Estimation

# **Description**

Build contrasts for factors with equal marginal priors on all levels. The 3 functions give the same orthogonal contrasts, but are scaled differently to allow different prior specifications (see 'Details'). Implementation from Singmann & Gronau's bfrms, following the description in Rouder, Morey, Speckman, & Province (2012, p. 363).

# Usage

```
contr.equalprior(n, contrasts = TRUE, sparse = FALSE)
contr.equalprior_pairs(n, contrasts = TRUE, sparse = FALSE)
contr.equalprior_deviations(n, contrasts = TRUE, sparse = FALSE)
```

# **Arguments**

n a vector of levels for a factor, or the number of levels.

contrasts a logical indicating whether contrasts should be computed.

sparse logical indicating if the result should be sparse (of class dgCMatrix), using package Matrix.

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#### **Details**

When using stats::contr.treatment, each dummy variable is the difference between each level and the reference level. While this is useful if setting different priors for each coefficient, it should not be used if one is trying to set a general prior for differences between means, as it (as well as stats::contr.sum and others) results in unequal marginal priors on the means the difference between them.

```
library(brms)
data <- data.frame(</pre>
 group = factor(rep(LETTERS[1:4], each = 3)),
 y = rnorm(12)
)
contrasts(data$group) # R's default contr.treatment
#> B C D
#> A 0 0 0
#> B 1 0 0
#> C 0 1 0
#> D 0 0 1
model_prior <- brm(</pre>
 y ~ group, data = data,
 sample_prior = "only",
 # Set the same priors on the 3 dummy variable
 # (Using an arbitrary scale)
  prior = set_prior("normal(0, 10)", coef = c("groupB", "groupC", "groupD"))
)
est <- emmeans::emmeans(model_prior, pairwise ~ group)</pre>
point_estimate(est, centr = "mean", disp = TRUE)
#> Point Estimate
#>
#> Parameter | Mean |
            | -0.01 | 6.35
#> A
#> B
           | -0.10 | 9.59
#> C
            | 0.11 | 9.55
#> D
            | -0.16 | 9.52
           | 0.10 | 9.94
#> A - B
#> A - C
           | -0.12 | 9.96
#> A - D
            | 0.15 | 9.87
#> B - C
            | -0.22 | 14.38
#> B - D
           | 0.05 | 14.14
#> C - D
            | 0.27 | 14.00
```

We can see that the priors for means aren't all the same (A having a more narrow prior), and likewise

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for the pairwise differences (priors for differences from A are more narrow).

The solution is to use one of the methods provided here, which *do* result in marginally equal priors on means differences between them. Though this will obscure the interpretation of parameters, setting equal priors on means and differences is important for they are useful for specifying equal priors on all means in a factor and their differences correct estimation of Bayes factors for contrasts and order restrictions of multi-level factors (where k>2). See info on specifying correct priors for factors with more than 2 levels in the Bayes factors vignette.

**NOTE:** When setting priors on these dummy variables, always:

- 1. Use priors that are **centered on 0**! Other location/centered priors are meaningless!
- 2. Use **identically-scaled priors** on all the dummy variables of a single factor!

contr. equalprior returns the original orthogonal-normal contrasts as described in Rouder, Morey, Speckman, & Province (2012, p. 363). Setting contrasts = FALSE returns the  $I_n - \frac{1}{n}$  matrix.

```
contr.equalprior_pairs:
```

Useful for setting priors in terms of pairwise differences between means - the scales of the priors defines the prior distribution of the pair-wise differences between all pairwise differences (e.g., A - B, B - C, etc.).

```
contrasts(data$group) <- contr.equalprior_pairs</pre>
contrasts(data$group)
#>
           [,1]
                      [,2]
                                 [,3]
#> A 0.0000000 0.6123724 0.0000000
#> B -0.1893048 -0.2041241 0.5454329
#> C -0.3777063 -0.2041241 -0.4366592
#> D 0.5670111 -0.2041241 -0.1087736
model_prior <- brm(</pre>
 y ~ group, data = data,
 sample_prior = "only",
 # Set the same priors on the 3 dummy variable
 # (Using an arbitrary scale)
 prior = set_prior("normal(0, 10)", coef = c("group1", "group2", "group3"))
)
est <- emmeans(model_prior, pairwise ~ group)</pre>
point_estimate(est, centr = "mean", disp = TRUE)
#> Point Estimate
#>
#> Parameter | Mean |
                          SD
             | -0.31 | 7.46
#> B
            | -0.24 | 7.47
#> C
            | -0.34 | 7.50
#> D
            | -0.30 | 7.25
#> A - B | -0.08 | 10.00
#> A - C
           | 0.03 | 10.03
```

All means have the same prior distribution, and the distribution of the differences matches the prior we set of "normal(0, 10)". Success!

```
contr.equalprior_deviations:
```

Useful for setting priors in terms of the deviations of each mean from the grand mean - the scales of the priors defines the prior distribution of the distance (above, below) the mean of one of the levels might have from the overall mean. (See examples.)

#### Value

A matrix with n rows and k columns, with k=n-1 if contrasts is TRUE and k=n if contrasts is FALSE.

#### References

Rouder, J. N., Morey, R. D., Speckman, P. L., & Province, J. M. (2012). Default Bayes factors for ANOVA designs. *Journal of Mathematical Psychology*, 56(5), 356-374. https://doi.org/10.1016/j.jmp.2012.08.001

# **Examples**

```
contr.equalprior(2) # Q_2 in Rouder et al. (2012, p. 363)

contr.equalprior(5) # equivalent to Q_5 in Rouder et al. (2012, p. 363)

## check decomposition
Q3 <- contr.equalprior(3)
Q3 %*% t(Q3) ## 2/3 on diagonal and -1/3 on off-diagonal elements</pre>
```

```
convert_bayesian_as_frequentist
```

Convert (refit) a Bayesian model to frequentist

# **Description**

Refit Bayesian model as frequentist. Can be useful for comparisons.

```
convert_bayesian_as_frequentist(model, data = NULL, REML = TRUE)
bayesian_as_frequentist(model, data = NULL, REML = TRUE)
```

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# Arguments

model A Bayesian model.

data Data used by the model. If NULL, will try to extract it from the model.

REML For mixed effects, should models be estimated using restricted maximum likeli-

hood (REML) (TRUE, default) or maximum likelihood (FALSE)?

#### **Examples**

```
# Rstanarm -----
# Simple regressions
model <- rstanarm::stan_glm(Sepal.Length ~ Species,</pre>
  data = iris, chains = 2, refresh = 0
bayesian_as_frequentist(model)
model <- rstanarm::stan_glm(vs ~ mpg,</pre>
  family = "binomial",
  data = mtcars, chains = 2, refresh = 0
)
bayesian_as_frequentist(model)
# Mixed models
model <- rstanarm::stan_glmer(</pre>
  Sepal.Length ~ Petal.Length + (1 | Species),
  data = iris, chains = 2, refresh = 0
bayesian_as_frequentist(model)
model <- rstanarm::stan_glmer(vs ~ mpg + (1 | cyl),</pre>
  family = "binomial",
  data = mtcars, chains = 2, refresh = 0
bayesian_as_frequentist(model)
```

density\_at

Density Probability at a Given Value

# **Description**

Compute the density value at a given point of a distribution (i.e., the value of the y axis of a value x of a distribution).

```
density_at(posterior, x, precision = 2^10, method = "kernel", ...)
```

## **Arguments**

posterior Vector representing a posterior distribution.

x The value of which to get the approximate probability.

precision Number of points of density data. See the n parameter in density.

method Density estimation method. Can be "kernel" (default), "logspline" or "KernSmooth".

Currently not used.

## **Examples**

```
library(bayestestR)
posterior <- distribution_normal(n = 10)
density_at(posterior, 0)
density_at(posterior, c(0, 1))</pre>
```

describe\_posterior

Describe Posterior Distributions

## **Description**

Compute indices relevant to describe and characterize the posterior distributions.

```
describe_posterior(posterior, ...)
## S3 method for class 'numeric'
describe_posterior(
 posterior,
  centrality = "median",
 dispersion = FALSE,
  ci = 0.95,
  ci_method = "eti",
  test = c("p_direction", "rope"),
  rope_range = "default",
  rope_ci = 0.95,
  keep_iterations = FALSE,
 bf_prior = NULL,
 BF = 1,
  verbose = TRUE,
)
## S3 method for class 'data.frame'
describe_posterior(
 posterior,
 centrality = "median",
```

```
dispersion = FALSE,
  ci = 0.95,
  ci_method = "eti",
  test = c("p_direction", "rope"),
  rope_range = "default",
  rope_ci = 0.95,
  keep_iterations = FALSE,
 bf_prior = NULL,
 BF = 1,
 rvar_col = NULL,
 verbose = TRUE,
)
## S3 method for class 'stanreg'
describe_posterior(
 posterior,
  centrality = "median",
 dispersion = FALSE,
  ci = 0.95,
  ci_method = "eti",
  test = c("p_direction", "rope"),
  rope_range = "default",
  rope_ci = 0.95,
  keep_iterations = FALSE,
 bf_prior = NULL,
  diagnostic = c("ESS", "Rhat"),
  priors = FALSE,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
 BF = 1,
  verbose = TRUE,
)
## S3 method for class 'brmsfit'
describe_posterior(
 posterior,
 centrality = "median",
 dispersion = FALSE,
  ci = 0.95,
  ci_method = "eti",
  test = c("p_direction", "rope"),
  rope_range = "default",
  rope_ci = 0.95,
  keep_iterations = FALSE,
```

```
bf_prior = NULL,
  diagnostic = c("ESS", "Rhat"),
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all", "location",
    "distributional", "auxiliary"),
  parameters = NULL,
 BF = 1,
  priors = FALSE,
  verbose = TRUE.
)
```

#### **Arguments**

posterior A vector, data frame or model of posterior draws. bayestestR supports a wide

range of models (see methods("describe\_posterior")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly

resemble the arguments of the .numeric method.

Additional arguments to be passed to or from methods.

The point-estimates (centrality indices) to compute. Character (vector) or list centrality with one or more of these options: "median", "mean", "MAP" (see map\_estimate()),

"trimmed" (which is just mean(x, trim = threshold)), "mode" or "all".

Logical, if TRUE, computes indices of dispersion related to the estimate(s) (SD dispersion

and MAD for mean and median, respectively). Dispersion is not available for "MAP" or "mode" centrality indices.

Value or vector of probability of the CI (between 0 and 1) to be estimated. Deci fault to 0.95 (95%).

ci\_method The type of index used for Credible Interval. Can be "ETI" (default, see eti()),

"HDI" (see hdi()), "BCI" (see bci()), "SPI" (see spi()), or "SI" (see si()).

test The indices of effect existence to compute. Character (vector) or list with one or

> more of these options: "p\_direction" (or "pd"), "rope", "p\_map", "p\_significance" (or "ps"), "p\_rope", "equivalence\_test" (or "equitest"), "bayesfactor" (or "bf") or "all" to compute all tests. For each "test", the corresponding **bayestestR** function is called (e.g. rope() or p\_direction()) and its results

included in the summary output.

ROPE's lower and higher bounds. Should be a vector of two values (e.g., rope\_range c(-0.1, 0.1)), "default" or a list of numeric vectors of the same length as

numbers of parameters. If "default", the bounds are set to x +- 0.1\*SD(response).

The Credible Interval (CI) probability, corresponding to the proportion of HDI, rope\_ci

to use for the percentage in ROPE.

keep\_iterations

If TRUE, will keep all iterations (draws) of bootstrapped or Bayesian models. They will be added as additional columns named iter\_1, iter\_2, .... You can reshape them to a long format by running reshape\_iterations().

bf\_prior Distribution representing a prior for the computation of Bayes factors / SI. Used if the input is a posterior, otherwise (in the case of models) ignored.

BF	The amount of support required to be included in the support interval.
verbose	Toggle off warnings.
rvar_col	A single character - the name of an rvar column in the data frame to be processed. See example in p_direction().
diagnostic	Diagnostic metrics to compute. Character (vector) or list with one or more of these options: "ESS", "Rhat", "MCSE" or "all".
priors	Add the prior used for each parameter.
effects	Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.
component	Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to <b>brms</b> -models.
parameters	Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like lp or prior_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output.

### **Details**

One or more components of point estimates (like posterior mean or median), intervals and tests can be omitted from the summary output by setting the related argument to NULL. For example, test = NULL and centrality = NULL would only return the HDI (or CI).

#### References

- Makowski, D., Ben-Shachar, M. S., Chen, S. H. A., and Lüdecke, D. (2019). *Indices of Effect Existence and Significance in the Bayesian Framework*. Frontiers in Psychology 2019;10:2767. doi:10.3389/fpsyg.2019.02767
- Region of Practical Equivalence (ROPE)
- · Bayes factors

```
library(bayestestR)

if (require("logspline")) {
    x <- rnorm(1000)
    describe_posterior(x, verbose = FALSE)
    describe_posterior(x,
        centrality = "all",
        dispersion = TRUE,
        test = "all",
        verbose = FALSE
)
    describe_posterior(x, ci = c(0.80, 0.90), verbose = FALSE)

df <- data.frame(replicate(4, rnorm(100)))
    describe_posterior(df, verbose = FALSE)</pre>
```

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```
describe_posterior(
   df,
   centrality = "all",
   dispersion = TRUE,
   test = "all",
   verbose = FALSE
 describe_posterior(df, ci = c(0.80, 0.90), verbose = FALSE)
 df <- data.frame(replicate(4, rnorm(20)))</pre>
 head(reshape_iterations(
   describe_posterior(df, keep_iterations = TRUE, verbose = FALSE)
 ))
}
# rstanarm models
# -----
if (require("rstanarm") && require("emmeans")) {
 model <- suppressWarnings(</pre>
   stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
 )
 describe_posterior(model)
 describe_posterior(model, centrality = "all", dispersion = TRUE, test = "all")
 describe_posterior(model, ci = c(0.80, 0.90))
 describe_posterior(model, rope_range = list(c(-10, 5), c(-0.2, 0.2), "default"))
 # emmeans estimates
 describe_posterior(emtrends(model, ~1, "wt"))
}
# BayesFactor objects
if (require("BayesFactor")) {
 bf \leftarrow ttestBF(x = rnorm(100, 1, 1))
 describe_posterior(bf)
 describe_posterior(bf, centrality = "all", dispersion = TRUE, test = "all")
 describe_posterior(bf, ci = c(0.80, 0.90))
}
```

describe\_prior

Describe Priors

### **Description**

Returns a summary of the priors used in the model.

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### Usage

```
describe_prior(model, ...)
## S3 method for class 'brmsfit'
describe_prior(
  model,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all", "location",
      "distributional", "auxiliary"),
  parameters = NULL,
    ...
)
```

### **Arguments**

model A Bayesian model. . . . Currently not used.

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like  $lp\_$  or  $prior\_$ ) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

diagnostic\_draws 43

```
describe_prior(bf)
}
```

diagnostic\_draws

Diagnostic values for each iteration

# Description

Returns the accumulated log-posterior, the average Metropolis acceptance rate, divergent transitions, treedepth rather than terminated its evolution normally.

# Usage

```
diagnostic_draws(posterior, ...)
```

## **Arguments**

```
posterior A stanreg, stanfit, brmsfit, or blavaan object.
... Currently not used.
```

## **Examples**

```
set.seed(333)

if (require("brms", quietly = TRUE)) {
   model <- suppressWarnings(brm(mpg ~ wt * cyl * vs,
        data = mtcars,
        iter = 100, control = list(adapt_delta = 0.80),
        refresh = 0
   ))
   diagnostic_draws(model)
}</pre>
```

# **Description**

Extract diagnostic metrics (Effective Sample Size (ESS), Rhat and Monte Carlo Standard Error MCSE).

#### Usage

```
diagnostic_posterior(posterior, ...)
## Default S3 method:
diagnostic_posterior(posterior, diagnostic = c("ESS", "Rhat"), ...)
## S3 method for class 'stanreg'
diagnostic_posterior(
  posterior,
  diagnostic = "all",
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
)
## S3 method for class 'brmsfit'
diagnostic_posterior(
  posterior,
  diagnostic = "all",
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL,
)
```

#### Arguments

diagnostic

effects

component

A stanreg, stanfit, brmsfit, or blavaan object. posterior

Currently not used.

Diagnostic metrics to compute. Character (vector) or list with one or more of these options: "ESS", "Rhat", "MCSE" or "all".

Should variables for fixed effects ("fixed"), random effects ("random") or both

("all") be returned? Only applies to mixed models. May be abbreviated. Which type of parameters to return, such as parameters for the conditional

model, the zero-inflated part of the model, the dispersion term, the instrumental variables or marginal effects be returned? Applies to models with zero-inflated and/or dispersion formula, or to models with instrumental variables (so called fixed-effects regressions), or models with marginal effects (from mfx). See details in section Model Components . May be abbreviated. Note that the conditional component also refers to the count or mean component - names may differ, depending on the modeling package. There are three convenient shortcuts (not applicable to *all* model classes):

- component = "all" returns all possible parameters.
- If component = "location", location parameters such as conditional, zero\_inflated, smooth\_terms, or instruments are returned (everything

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that are fixed or random effects - depending on the effects argument - but no auxiliary parameters).

• For component = "distributional" (or "auxiliary"), components like sigma, dispersion, beta or precision (and other auxiliary parameters) are returned.

parameters

Regular expression pattern that describes the parameters that should be returned.

### **Details**

**Effective Sample (ESS)** should be as large as possible, although for most applications, an effective sample size greater than 1000 is sufficient for stable estimates (*Bürkner, 2017*). The ESS corresponds to the number of independent samples with the same estimation power as the N autocorrelated samples. It is a measure of "how much independent information there is in autocorrelated chains" (*Kruschke 2015, p182-3*).

**Rhat** should be the closest to 1. It should not be larger than 1.1 (*Gelman and Rubin*, 1992) or 1.01 (*Vehtari et al.*, 2019). The split Rhat statistic quantifies the consistency of an ensemble of Markov chains.

Monte Carlo Standard Error (MCSE) is another measure of accuracy of the chains. It is defined as standard deviation of the chains divided by their effective sample size (the formula for mcse() is from Kruschke 2015, p. 187). The MCSE "provides a quantitative suggestion of how big the estimation noise is".

#### References

- Gelman, A., & Rubin, D. B. (1992). Inference from iterative simulation using multiple sequences. Statistical science, 7(4), 457-472.
- Vehtari, A., Gelman, A., Simpson, D., Carpenter, B., and Bürkner, P. C. (2019). Rank-normalization, folding, and localization: An improved Rhat for assessing convergence of MCMC. arXiv preprint arXiv:1903.08008.
- Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press.

```
# rstanarm models
# ------
model <- suppressWarnings(
    rstanarm::stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
)
diagnostic_posterior(model)

# brms models
# -------
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)
diagnostic_posterior(model)</pre>
```

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disgust

Moral Disgust Judgment

## **Description**

A sample (simulated) dataset, used in tests and some examples.

#### **Format**

A data frame with 500 rows and 5 variables:

**score** Score on the questionnaire, which ranges from 0 to 50 with higher scores representing harsher moral judgment

**condition** one of three conditions, differing by the odor present in the room: a pleasant scent associated with cleanliness (lemon), a disgusting scent (sulfur), and a control condition in which no unusual odor is present

```
data("disgust")
head(disgust, n = 5)
     score condition
#> 1
       13
            control
       26
#> 2
            control
#> 3
       30
            control
#> 4
       23
            control
#> 5
       34
            control
```

# Author(s)

Richard D. Morey

distribution

**Empirical Distributions** 

## **Description**

Generate a sequence of n-quantiles, i.e., a sample of size n with a near-perfect distribution.

```
distribution(type = "normal", ...)
distribution_custom(n, type = "norm", ..., random = FALSE)
distribution_beta(n, shape1, shape2, ncp = 0, random = FALSE, ...)
```

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```
distribution_binomial(n, size = 1, prob = 0.5, random = FALSE, ...)
distribution_binom(n, size = 1, prob = 0.5, random = FALSE, ...)
distribution_cauchy(n, location = 0, scale = 1, random = FALSE, ...)
distribution_chisquared(n, df, ncp = 0, random = FALSE, ...)
distribution_chisq(n, df, ncp = 0, random = FALSE, ...)
distribution_gamma(n, shape, scale = 1, random = FALSE, ...)
distribution_mixture_normal(n, mean = c(-3, 3), sd = 1, random = FALSE, ...)
distribution_normal(n, mean = 0, sd = 1, random = FALSE, ...)
distribution_gaussian(n, mean = 0, sd = 1, random = FALSE, ...)
distribution_nbinom(n, size, prob, mu, phi, random = FALSE, ...)
distribution_poisson(n, lambda = 1, random = FALSE, ...)
distribution_student(n, df, ncp, random = FALSE, ...)
distribution_t(n, df, ncp, random = FALSE, ...)
distribution_student_t(n, df, ncp, random = FALSE, ...)
distribution_tweedie(n, xi = NULL, mu, phi, power = NULL, random = FALSE, ...)
distribution_uniform(n, min = 0, max = 1, random = FALSE, ...)
rnorm_perfect(n, mean = 0, sd = 1)
```

### **Arguments**

type

-	"beta".
	Arguments passed to or from other methods.
n	the number of observations
random	Generate near-perfect or random (simple wrappers for the base R $r*$ functions) distributions.
shape1, shape2	non-negative parameters of the Beta distribution.
ncp	non-centrality parameter.
size	number of trials (zero or more).
prob	probability of success on each trial.

Can be any of the names from base R's Distributions, like "cauchy", "pois" or

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location, scale location and scale parameters.

df degrees of freedom (non-negative, but can be non-integer).

shape Shape parameter. mean vector of means.

sd vector of standard deviations.

mu the mean

phi Corresponding to glmmTMB's implementation of nbinom distribution, where size=mu/phi.

lambda vector of (non-negative) means.

xi For tweedie distributions, the value of xi such that the variance is var(Y) = phi

\* mu^xi.

power Alias for xi.

min, max lower and upper limits of the distribution. Must be finite.

#### **Details**

When random = FALSE, these function return q\*(ppoints(n), ...).

## **Examples**

```
library(bayestestR)
x <- distribution(n = 10)
plot(density(x))

x <- distribution(type = "gamma", n = 100, shape = 2)
plot(density(x))</pre>
```

effective\_sample

Effective Sample Size (ESS)

# Description

This function returns the effective sample size (ESS).

```
effective_sample(model, ...)

## S3 method for class 'brmsfit'
effective_sample(
   model,
   effects = c("fixed", "random", "all"),
   component = c("conditional", "zi", "zero_inflated", "all"),
   parameters = NULL,
   ...
)
```

effective\_sample 49

```
## S3 method for class 'stanreg'
effective_sample(
  model,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
        "distributional", "auxiliary"),
  parameters = NULL,
    ...
)
```

#### **Arguments**

model A stanreg, stanfit, brmsfit, blavaan, or MCMCglmm object.

... Currently not used.

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like lp\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

#### **Details**

**Effective Sample (ESS)** should be as large as possible, altough for most applications, an effective sample size greater than 1,000 is sufficient for stable estimates (Bürkner, 2017). The ESS corresponds to the number of independent samples with the same estimation power as the N autocorrelated samples. It is a measure of "how much independent information there is in autocorrelated chains" (*Kruschke 2015*, p182-3).

## Value

A data frame with two columns: Parameter name and effective sample size (ESS).

## References

- Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press.
- Bürkner, P. C. (2017). brms: An R package for Bayesian multilevel models using Stan. Journal of Statistical Software, 80(1), 1-28

```
library(rstanarm)
```

```
model <- suppressWarnings(
   stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
)
effective_sample(model)</pre>
```

equivalence\_test

Test for Practical Equivalence

## **Description**

Perform a **Test for Practical Equivalence** for Bayesian and frequentist models.

```
equivalence_test(x, ...)
## Default S3 method:
equivalence_test(x, ...)
## S3 method for class 'data.frame'
equivalence_test(
 х,
 range = "default",
  ci = 0.95,
  rvar_col = NULL,
 verbose = TRUE,
)
## S3 method for class 'stanreg'
equivalence_test(
 range = "default",
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'brmsfit'
equivalence_test(
 х,
```

```
range = "default",
ci = 0.95,
effects = c("fixed", "random", "all"),
component = c("conditional", "zi", "zero_inflated", "all"),
parameters = NULL,
verbose = TRUE,
...
)
```

### **Arguments**

x Vector representing a posterior distribution. Can also be a stanneg or brmsfit model.

... Currently not used.

range

rvar\_col

ROPE's lower and higher bounds. Should be "default" or depending on the number of outcome variables a vector or a list. For models with one response, range can be:

- a vector of length two (e.g., c(-0.1, 0.1)),
- a list of numeric vector of the same length as numbers of parameters (see 'Examples').
- a list of *named* numeric vectors, where names correspond to parameter names. In this case, all parameters that have no matching name in range will be set to "default".

In multivariate models, range should be a list with another list (one for each response variable) of numeric vectors. Vector names should correspond to the name of the response variables. If "default" and input is a vector, the range is set to c(-0.1, 0.1). If "default" and input is a Bayesian model, rope\_range() is used. See 'Examples'.

ci The Credible Interval (CI) probability, corresponding to the proportion of HDI, to use for the percentage in ROPE.

A single character - the name of an rvar column in the data frame to be processed. See example in p\_direction().

verbose Toggle off warnings.

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to **brms**-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like  $lp\_$  or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

### **Details**

Documentation is accessible for:

- · Bayesian models
- · Frequentist models

For Bayesian models, the **Test for Practical Equivalence** is based on the "HDI+ROPE decision rule" (Kruschke, 2014, 2018) to check whether parameter values should be accepted or rejected against an explicitly formulated "null hypothesis" (i.e., a ROPE). In other words, it checks the percentage of the 89% HDI that is the null region (the ROPE). If this percentage is sufficiently low, the null hypothesis is rejected. If this percentage is sufficiently high, the null hypothesis is accepted.

Using the ROPE and the HDI, Kruschke (2018) suggests using the percentage of the 95% (or 89%, considered more stable) HDI that falls within the ROPE as a decision rule. If the HDI is completely outside the ROPE, the "null hypothesis" for this parameter is "rejected". If the ROPE completely covers the HDI, i.e., all most credible values of a parameter are inside the region of practical equivalence, the null hypothesis is accepted. Else, it's undecided whether to accept or reject the null hypothesis. If the full ROPE is used (i.e., 100% of the HDI), then the null hypothesis is rejected or accepted if the percentage of the posterior within the ROPE is smaller than to 2.5% or greater than 97.5%. Desirable results are low proportions inside the ROPE (the closer to zero the better).

Some attention is required for finding suitable values for the ROPE limits (argument range). See 'Details' in rope\_range() for further information.

### Multicollinearity: Non-independent covariates

When parameters show strong correlations, i.e. when covariates are not independent, the joint parameter distributions may shift towards or away from the ROPE. In such cases, the test for practical equivalence may have inappropriate results. Collinearity invalidates ROPE and hypothesis testing based on univariate marginals, as the probabilities are conditional on independence. Most problematic are the results of the "undecided" parameters, which may either move further towards "rejection" or away from it (*Kruschke 2014, 340f*).

equivalence\_test() performs a simple check for pairwise correlations between parameters, but as there can be collinearity between more than two variables, a first step to check the assumptions of this hypothesis testing is to look at different pair plots. An even more sophisticated check is the projection predictive variable selection (*Piironen and Vehtari 2017*).

### Value

A data frame with following columns:

- Parameter The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- CI The probability of the HDI.
- ROPE\_low, ROPE\_high The limits of the ROPE. These values are identical for all parameters.
- ROPE\_Percentage The proportion of the HDI that lies inside the ROPE.
- ROPE\_Equivalence The "test result", as character. Either "rejected", "accepted" or "undecided".
- HDI\_low, HDI\_high The lower and upper HDI limits for the parameters.

#### Note

There is a print()-method with a digits-argument to control the amount of digits in the output, and there is a plot()-method to visualize the results from the equivalence-test (for models only).

#### References

- Kruschke, J. K. (2018). Rejecting or accepting parameter values in Bayesian estimation. Advances in Methods and Practices in Psychological Science, 1(2), 270-280. doi:10.1177/2515245918771304
- Kruschke, J. K. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press
- Piironen, J., & Vehtari, A. (2017). Comparison of Bayesian predictive methods for model selection. Statistics and Computing, 27(3), 711–735. doi:10.1007/s112220169649y

```
library(bayestestR)
equivalence_test(x = rnorm(1000, 0, 0.01), range = c(-0.1, 0.1))
equivalence_test(x = rnorm(1000, 0, 1), range = c(-0.1, 0.1))
equivalence_test(x = rnorm(1000, 1, 0.01), range = c(-0.1, 0.1))
equivalence_test(x = rnorm(1000, 1, 1), ci = c(.50, .99))
# print more digits
test <- equivalence_test(x = rnorm(1000, 1, 1), ci = c(.50, .99))
print(test, digits = 4)
model <- rstanarm::stan_glm(mpg ~ wt + cyl, data = mtcars)</pre>
equivalence_test(model)
# multiple ROPE ranges - asymmetric, symmetric, default
equivalence_test(model, range = list(c(10, 40), c(-5, -4), "default"))
# named ROPE ranges
equivalence_test(model, range = list(wt = c(-5, -4), `(Intercept)` = c(10, 40)))
# plot result
test <- equivalence_test(model)</pre>
plot(test)
equivalence_test(emmeans::emtrends(model, ~1, "wt", data = mtcars))
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
equivalence_test(model)
bf <- BayesFactor::ttestBF(x = rnorm(100, 1, 1))</pre>
# equivalence_test(bf)
```

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estimate\_density

Density Estimation

### **Description**

This function is a wrapper over different methods of density estimation. By default, it uses the base R density with by default uses a different smoothing bandwidth ("SJ") from the legacy default implemented the base R density function ("nrd0"). However, Deng and Wickham suggest that method = "KernSmooth" is the fastest and the most accurate.

## Usage

```
estimate_density(x, ...)
## S3 method for class 'data.frame'
estimate_density(
    x,
    method = "kernel",
    precision = 2^10,
    extend = FALSE,
    extend_scale = 0.1,
    bw = "SJ",
    ci = NULL,
    select = NULL,
    by = NULL,
    rvar_col = NULL,
    ...
)
```

## Arguments

Х	Vector representing a posterior distribution, or a data frame of such vectors. Can
	also be a Bayesian model. bayestestR supports a wide range of models (see, for
	example, methods("hdi")) and not all of those are documented in the 'Usage'
	section, because methods for other classes mostly resemble the arguments of the
	.numeric or .data.framemethods.

... Currently not used.

method Density estimation method. Can be "kernel" (default), "logspline" or "KernSmooth".

precision Number of points of density data. See the n parameter in density.

extend Extend the range of the x axis by a factor of extend\_scale.

extend\_scale Ratio of range by which to extend the x axis. A value of 0.1 means that the x

axis will be extended by 1/10 of the range of the data.

bw See the eponymous argument in density. Here, the default has been changed

for "SJ", which is recommended.

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ci	The confidence interval threshold. Only used when method = "kernel". This feature is experimental, use with caution.
select	Character vector of column names. If NULL (the default), all numeric variables will be selected. Other arguments from datawizard::extract_column_names() (such as exclude) can also be used.
by	Optional character vector. If not NULL and input is a data frame, density estimation is performed for each group (subsets) indicated by by. See examples.
at	Deprecated in favour of by.
rvar_col	A single character - the name of an rvar column in the data frame to be processed. See example in p_direction().

### Note

There is also a plot()-method implemented in the **see**-package.

#### References

Deng, H., & Wickham, H. (2011). Density estimation in R. Electronic publication.

```
library(bayestestR)
set.seed(1)
x <- rnorm(250, mean = 1)
# Basic usage
density_kernel <- estimate_density(x) # default method is "kernel"</pre>
hist(x, prob = TRUE)
lines(density_kernel$x, density_kernel$y, col = "black", lwd = 2)
lines(density_kernel$x, density_kernel$CI_low, col = "gray", lty = 2)
lines(density_kernel$x, density_kernel$CI_high, col = "gray", lty = 2)
legend("topright",
  legend = c("Estimate", "95% CI"),
  col = c("black", "gray"), lwd = 2, lty = c(1, 2)
)
# Other Methods
density_logspline <- estimate_density(x, method = "logspline")</pre>
density_KernSmooth <- estimate_density(x, method = "KernSmooth")</pre>
density_mixture <- estimate_density(x, method = "mixture")</pre>
hist(x, prob = TRUE)
lines(density_kernel$x, density_kernel$y, col = "black", lwd = 2)
lines(density_logspline$x, density_logspline$y, col = "red", lwd = 2)
lines(density_KernSmooth$x, density_KernSmooth$y, col = "blue", lwd = 2)
lines(density_mixture$x, density_mixture$y, col = "green", lwd = 2)
# Extension
```

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```
density_extended <- estimate_density(x, extend = TRUE)</pre>
density_default <- estimate_density(x, extend = FALSE)</pre>
hist(x, prob = TRUE)
lines(density_extended$x, density_extended$y, col = "red", lwd = 3)
lines(density_default$x, density_default$y, col = "black", lwd = 3)
# Multiple columns
head(estimate_density(iris))
head(estimate_density(iris, select = "Sepal.Width"))
# Grouped data
head(estimate_density(iris, by = "Species"))
head(estimate_density(iris$Petal.Width, by = iris$Species))
# rstanarm models
# -----
library(rstanarm)
model <- suppressWarnings(</pre>
 stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
head(estimate_density(model))
library(emmeans)
head(estimate_density(emtrends(model, ~1, "wt", data = mtcars)))
# brms models
# -----
library(brms)
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
estimate_density(model)
```

eti

Equal-Tailed Interval (ETI)

### **Description**

Compute the **Equal-Tailed Interval (ETI)** of posterior distributions using the quantiles method. The probability of being below this interval is equal to the probability of being above it. The ETI can be used in the context of uncertainty characterisation of posterior distributions as **Credible Interval (CI)**.

```
eti(x, ...)
## S3 method for class 'numeric'
eti(x, ci = 0.95, verbose = TRUE, ...)
```

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```
## S3 method for class 'data.frame'
eti(x, ci = 0.95, rvar\_col = NULL, verbose = TRUE, ...)
## S3 method for class 'stanreg'
eti(
  х.
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'brmsfit'
  Х,
  ci = 0.95.
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'get_predicted'
eti(x, ci = 0.95, use_iterations = FALSE, verbose = TRUE, ...)
```

## **Arguments**

v Vector representing a posterior distribution, or a data frame of such vectors. Can also be a Bayesian model. bayestestR supports a wide range of models (see, for example, methods("hdi")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly resemble the arguments of the .numeric or .data.framemethods.

.. Currently not used.

ci Value or vector of probability of the (credible) interval - CI (between 0 and 1) to

be estimated. Default to .95 (95%).

verbose Toggle off warnings.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

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parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like lp\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()),

the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

#### **Details**

Unlike equal-tailed intervals (see eti()) that typically exclude 2.5% from each tail of the distribution and always include the median, the HDI is *not* equal-tailed and therefore always includes the mode(s) of posterior distributions. While this can be useful to better represent the credibility mass of a distribution, the HDI also has some limitations. See spi() for details.

The 95% or 89% Credible Intervals (CI) are two reasonable ranges to characterize the uncertainty related to the estimation (see here for a discussion about the differences between these two values).

The 89% intervals (ci = 0.89) are deemed to be more stable than, for instance, 95% intervals (*Kruschke, 2014*). An effective sample size of at least 10.000 is recommended if one wants to estimate 95% intervals with high precision (*Kruschke, 2014, p. 183ff*). Unfortunately, the default number of posterior samples for most Bayes packages (e.g., rstanarm or brms) is only 4.000 (thus, you might want to increase it when fitting your model). Moreover, 89 indicates the arbitrariness of interval limits - its only remarkable property is being the highest prime number that does not exceed the already unstable 95% threshold (*McElreath, 2015*).

However, 95% has some advantages too. For instance, it shares (in the case of a normal posterior distribution) an intuitive relationship with the standard deviation and it conveys a more accurate image of the (artificial) bounds of the distribution. Also, because it is wider, it makes analyses more conservative (i.e., the probability of covering 0 is larger for the 95% CI than for lower ranges such as 89%), which is a good thing in the context of the reproducibility crisis.

A 95% equal-tailed interval (ETI) has 2.5% of the distribution on either side of its limits. It indicates the 2.5th percentile and the 97.5h percentile. In symmetric distributions, the two methods of computing credible intervals, the ETI and the HDI, return similar results.

This is not the case for skewed distributions. Indeed, it is possible that parameter values in the ETI have lower credibility (are less probable) than parameter values outside the ETI. This property seems undesirable as a summary of the credible values in a distribution.

On the other hand, the ETI range does change when transformations are applied to the distribution (for instance, for a log odds scale to probabilities): the lower and higher bounds of the transformed distribution will correspond to the transformed lower and higher bounds of the original distribution. On the contrary, applying transformations to the distribution will change the resulting HDI.

#### Value

A data frame with following columns:

- Parameter The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- CI The probability of the credible interval.
- CI\_low, CI\_high The lower and upper credible interval limits for the parameters.

### See Also

```
Other ci: bci(), ci(), hdi(), si(), spi()
```

### **Examples**

```
library(bayestestR)
posterior <- rnorm(1000)</pre>
eti(posterior)
eti(posterior, ci = c(0.80, 0.89, 0.95))
df <- data.frame(replicate(4, rnorm(100)))</pre>
eti(df, ci = c(0.80, 0.89, 0.95))
model <- suppressWarnings(</pre>
  rstanarm::stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
eti(model)
eti(model, ci = c(0.80, 0.89, 0.95))
eti(emmeans::emtrends(model, ~1, "wt", data = mtcars))
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
eti(model)
eti(model, ci = c(0.80, 0.89, 0.95))
bf <- BayesFactor::ttestBF(x = rnorm(100, 1, 1))
eti(bf)
eti(bf, ci = c(0.80, 0.89, 0.95))
```

hdi

Highest Density Interval (HDI)

### **Description**

Compute the **Highest Density Interval (HDI)** of posterior distributions. All points within this interval have a higher probability density than points outside the interval. The HDI can be used in the context of uncertainty characterisation of posterior distributions as **Credible Interval (CI)**.

```
hdi(x, ...)
## S3 method for class 'numeric'
hdi(x, ci = 0.95, verbose = TRUE, ...)
```

```
## S3 method for class 'data.frame'
hdi(x, ci = 0.95, rvar\_col = NULL, verbose = TRUE, ...)
## S3 method for class 'stanreg'
hdi(
  х,
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'brmsfit'
hdi(
  Х,
  ci = 0.95,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'get_predicted'
hdi(x, ci = 0.95, use_iterations = FALSE, verbose = TRUE, ...)
```

## **Arguments**

Χ	Vector representing a posterior distribution, or a data frame of such vectors. Can
	also be a Bayesian model. bayestestR supports a wide range of models (see, for
	example, methods("hdi")) and not all of those are documented in the 'Usage'
	section, because methods for other classes mostly resemble the arguments of the
	numeric or .data.framemethods.

... Currently not used.

Value or vector of probability of the (credible) interval - CI (between 0 and 1) to

be estimated. Default to .95 (95%).

verbose Toggle off warnings.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like lp\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()),

the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

#### **Details**

Unlike equal-tailed intervals (see eti()) that typically exclude 2.5% from each tail of the distribution and always include the median, the HDI is *not* equal-tailed and therefore always includes the mode(s) of posterior distributions. While this can be useful to better represent the credibility mass of a distribution, the HDI also has some limitations. See spi() for details.

The 95% or 89% Credible Intervals (CI) are two reasonable ranges to characterize the uncertainty related to the estimation (see here for a discussion about the differences between these two values).

The 89% intervals (ci = 0.89) are deemed to be more stable than, for instance, 95% intervals (*Kruschke*, 2014). An effective sample size of at least 10.000 is recommended if one wants to estimate 95% intervals with high precision (*Kruschke*, 2014, p. 183ff). Unfortunately, the default number of posterior samples for most Bayes packages (e.g., rstanarm or brms) is only 4.000 (thus, you might want to increase it when fitting your model). Moreover, 89 indicates the arbitrariness of interval limits - its only remarkable property is being the highest prime number that does not exceed the already unstable 95% threshold (*McElreath*, 2015).

However, 95% has some advantages too. For instance, it shares (in the case of a normal posterior distribution) an intuitive relationship with the standard deviation and it conveys a more accurate image of the (artificial) bounds of the distribution. Also, because it is wider, it makes analyses more conservative (i.e., the probability of covering 0 is larger for the 95% CI than for lower ranges such as 89%), which is a good thing in the context of the reproducibility crisis.

A 95% equal-tailed interval (ETI) has 2.5% of the distribution on either side of its limits. It indicates the 2.5th percentile and the 97.5h percentile. In symmetric distributions, the two methods of computing credible intervals, the ETI and the HDI, return similar results.

This is not the case for skewed distributions. Indeed, it is possible that parameter values in the ETI have lower credibility (are less probable) than parameter values outside the ETI. This property seems undesirable as a summary of the credible values in a distribution.

On the other hand, the ETI range does change when transformations are applied to the distribution (for instance, for a log odds scale to probabilities): the lower and higher bounds of the transformed distribution will correspond to the transformed lower and higher bounds of the original distribution. On the contrary, applying transformations to the distribution will change the resulting HDI.

#### Value

A data frame with following columns:

- Parameter The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- CI The probability of the credible interval.
- CI\_low, CI\_high The lower and upper credible interval limits for the parameters.

#### Note

There is also a plot()-method implemented in the see-package.

### Author(s)

Credits go to **ggdistribute** and **HDInterval**.

### References

- Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press.
- McElreath, R. (2015). Statistical rethinking: A Bayesian course with examples in R and Stan. Chapman and Hall/CRC.

#### See Also

```
Other interval functions, such as hdi(), eti(), bci(), spi(), si().

Other ci: bci(), ci(), eti(), si(), spi()
```

```
library(bayestestR)
posterior <- rnorm(1000)</pre>
hdi(posterior, ci = 0.89)
hdi(posterior, ci = c(0.80, 0.90, 0.95))
bayestestR::hdi(iris[1:4])
bayestestR::hdi(iris[1:4], ci = c(0.80, 0.90, 0.95))
model <- suppressWarnings(</pre>
  rstanarm::stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
bayestestR::hdi(model)
bayestestR::hdi(model, ci = c(0.80, 0.90, 0.95))
bayestestR::hdi(emmeans::emtrends(model, ~1, "wt", data = mtcars))
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
bayestestR::hdi(model)
bayestestR::hdi(model, ci = c(0.80, 0.90, 0.95))
bf <- BayesFactor::ttestBF(x = rnorm(100, 1, 1))</pre>
bayestestR::hdi(bf)
bayestestR::hdi(bf, ci = c(0.80, 0.90, 0.95))
```

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map\_estimate

Maximum A Posteriori probability estimate (MAP)

### **Description**

Find the **Highest Maximum A Posteriori probability estimate** (MAP) of a posterior, i.e., the value associated with the highest probability density (the "peak" of the posterior distribution). In other words, it is an estimation of the *mode* for continuous parameters. Note that this function relies on <code>estimate\_density()</code>, which by default uses a different smoothing bandwidth ("SJ") compared to the legacy default implemented the base R density() function ("nrd0").

```
map_estimate(x, ...)
## S3 method for class 'numeric'
map_estimate(x, precision = 2^10, method = "kernel", ...)
## S3 method for class 'stanreg'
map_estimate(
  Х,
  precision = 2^10,
  method = "kernel"
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
)
## S3 method for class 'brmsfit'
map_estimate(
  х,
  precision = 2^10,
  method = "kernel"
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL,
)
## S3 method for class 'data.frame'
map_estimate(x, precision = 2^10, method = "kernel", rvar_col = NULL, ...)
## S3 method for class 'get_predicted'
map_estimate(
 х,
```

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```
precision = 2^10,
method = "kernel",
use_iterations = FALSE,
verbose = TRUE,
...
)
```

#### **Arguments**

Vector representing a posterior distribution, or a data frame of such vectors. Can Х also be a Bayesian model. **bayestestR** supports a wide range of models (see, for example, methods("hdi")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly resemble the arguments of the .numeric or .data.framemethods. Currently not used. precision Number of points of density data. See the n parameter in density. Density estimation method. Can be "kernel" (default), "logspline" or "KernSmooth". method effects Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated. component Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to brms-models. Regular expression pattern that describes the parameters that should be returned. parameters Meta-parameters (like lp\_\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output. A single character - the name of an rvar column in the data frame to be prorvar\_col cessed. See example in p\_direction(). use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()), the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

# Value

verbose

A numeric value if x is a vector. If x is a model-object, returns a data frame with following columns:

- Parameter: The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- MAP\_Estimate: The MAP estimate for the posterior or each model parameter.

Toggle off warnings.

```
library(bayestestR)

posterior <- rnorm(10000)</pre>
```

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```
map_estimate(posterior)
plot(density(posterior))
abline(v = as.numeric(map_estimate(posterior)), col = "red")
model <- rstanarm::stan_glm(mpg ~ wt + cyl, data = mtcars)
map_estimate(model)
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)
map_estimate(model)</pre>
```

mcse

*Monte-Carlo Standard Error (MCSE)* 

## **Description**

This function returns the Monte Carlo Standard Error (MCSE).

#### Usage

```
mcse(model, ...)
## S3 method for class 'stanreg'
mcse(
  model,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
      "distributional", "auxiliary"),
  parameters = NULL,
  ...
)
```

### **Arguments**

model A stanreg, stanfit, brmsfit, blavaan, or MCMCglmm object.

Currently not used.

Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.

Component Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to brms-models.

Parameters Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like lp\_ or prior are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output.

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### **Details**

Monte Carlo Standard Error (MCSE) is another measure of accuracy of the chains. It is defined as standard deviation of the chains divided by their effective sample size (the formula for mcse() is from Kruschke 2015, p. 187). The MCSE "provides a quantitative suggestion of how big the estimation noise is".

#### References

Kruschke, J. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press

### **Examples**

```
library(bayestestR)

model <- suppressWarnings(
   rstanarm::stan_glm(mpg ~ wt + am, data = mtcars, chains = 1, refresh = 0)
)
mcse(model)</pre>
```

mediation

Summary of Bayesian multivariate-response mediation-models

## **Description**

mediation() is a short summary for multivariate-response mediation-models, i.e. this function computes average direct and average causal mediation effects of multivariate response models.

```
mediation(model, ...)

## S3 method for class 'brmsfit'
mediation(
  model,
    treatment,
  mediator,
  response = NULL,
  centrality = "median",
  ci = 0.95,
  method = "ETI",
  ...
)

## S3 method for class 'stanmvreg'
```

mediation 67

```
mediation(
  model,
  treatment,
  mediator,
  response = NULL,
  centrality = "median",
  ci = 0.95,
  method = "ETI",
  ...
)
```

## **Arguments**

model A brmsfit or stanmvreg object.

... Not used.

treatment Character, name of the treatment variable (or direct effect) in a (multivariate

response) mediator-model. If missing, mediation() tries to find the treatment

variable automatically, however, this may fail.

mediator Character, name of the mediator variable in a (multivariate response) mediator-

model. If missing, mediation() tries to find the treatment variable automati-

cally, however, this may fail.

response A named character vector, indicating the names of the response variables to be

used for the mediation analysis. Usually can be NULL, in which case these variables are retrieved automatically. If not NULL, names should match the names of the model formulas, names(insight::find\_response(model, combine = TRUE)). This can be useful if, for instance, the mediator variable used as predictor has a different name from the mediator variable used as response. This might occur when the mediator is transformed in one model, but used "as is" as response variable in the other model. Example: The mediator m is used as response variable, but the centered version m\_center is used as mediator variable. The second response variable (for the treatment model, with the mediator as additional predictor), y, is not transformed. Then we could use response like

this: mediation(model, response = c(m = "m\_center", y = "y")).

The point-estimates (centrality indices) to compute. Character (vector) or list with one or more of these options: "median", "mean", "MAP" (see map\_estimate()),

"trimmed" (which is just mean(x, trim = threshold)), "mode" or "all".

ci Value or vector of probability of the CI (between 0 and 1) to be estimated. De-

fault to 0.95 (95%).

method Can be "ETI" (default), "HDI", "BCI", "SPI" or "SI".

#### **Details**

centrality

mediation() returns a data frame with information on the *direct effect* (mean value of posterior samples from treatment of the outcome model), *mediator effect* (mean value of posterior samples from mediator of the outcome model), *indirect effect* (mean value of the multiplication of the posterior samples from mediator of the outcome model and the posterior samples from treatment

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of the mediation model) and the total effect (mean value of sums of posterior samples used for the direct and indirect effect). The *proportion mediated* is the indirect effect divided by the total effect.

For all values, the 89% credible intervals are calculated by default. Use ci to calculate a different interval.

The arguments treatment and mediator do not necessarily need to be specified. If missing, mediation() tries to find the treatment and mediator variable automatically. If this does not work, specify these variables.

The direct effect is also called *average direct effect* (ADE), the indirect effect is also called *average causal mediation effects* (ACME). See also *Tingley et al. 2014* and *Imai et al. 2010*.

#### Value

A data frame with direct, indirect, mediator and total effect of a multivariate-response mediation-model, as well as the proportion mediated. The effect sizes are median values of the posterior samples (use centrality for other centrality indices).

#### Note

There is an as.data.frame() method that returns the posterior samples of the effects, which can be used for further processing in the different **bayestestR** package.

#### References

- Imai, K., Keele, L. and Tingley, D. (2010) A General Approach to Causal Mediation Analysis, Psychological Methods, Vol. 15, No. 4 (December), pp. 309-334.
- Tingley, D., Yamamoto, T., Hirose, K., Imai, K. and Keele, L. (2014). mediation: R package for Causal Mediation Analysis, Journal of Statistical Software, Vol. 59, No. 5, pp. 1-38.

#### See Also

The **mediation** package for a causal mediation analysis in the frequentist framework.

```
library(mediation)
library(brms)
library(rstanarm)

# load sample data
data(jobs)
set.seed(123)

# linear models, for mediation analysis
b1 <- lm(job_seek ~ treat + econ_hard + sex + age, data = jobs)
b2 <- lm(depress2 ~ treat + job_seek + econ_hard + sex + age, data = jobs)
# mediation analysis, for comparison with Stan models
m1 <- mediate(b1, b2, sims = 1000, treat = "treat", mediator = "job_seek")
# Fit Bayesian mediation model in brms</pre>
```

model\_to\_priors 69

```
f1 <- bf(job_seek ~ treat + econ_hard + sex + age)
f2 <- bf(depress2 ~ treat + job_seek + econ_hard + sex + age)
m2 <- brm(f1 + f2 + set_rescor(FALSE), data = jobs, refresh = 0)

# Fit Bayesian mediation model in rstanarm
m3 <- suppressWarnings(stan_mvmer(
    list(
        job_seek ~ treat + econ_hard + sex + age + (1 | occp),
        depress2 ~ treat + job_seek + econ_hard + sex + age + (1 | occp)
    ),
    data = jobs,
    refresh = 0
))

summary(m1)
mediation(m2, centrality = "mean", ci = 0.95)
mediation(m3, centrality = "mean", ci = 0.95)</pre>
```

model\_to\_priors

Convert model's posteriors to priors (EXPERIMENTAL)

### **Description**

Convert model's posteriors to (normal) priors.

#### Usage

```
model_to_priors(model, scale_multiply = 3, ...)
```

### **Arguments**

model A Bayesian model.

scale\_multiply The SD of the posterior will be multiplied by this amount before being set as a prior to avoid overly narrow priors.

Other arguments for insight::get\_prior() or describe\_posterior.

```
# brms models
# -----
if (require("brms")) {
  formula <- brms::brmsformula(mpg ~ wt + cyl, center = FALSE)

model <- brms::brm(formula, data = mtcars, refresh = 0)
  priors <- model_to_priors(model)
  priors <- brms::validate_prior(priors, formula, data = mtcars)
  priors</pre>
```

70 overlap

```
model2 <- brms::brm(formula, data = mtcars, prior = priors, refresh = 0)
}</pre>
```

overlap

Overlap Coefficient

## **Description**

A method to calculate the overlap coefficient between two empirical distributions (that can be used as a measure of similarity between two samples).

## Usage

```
overlap(
    X,
    y,
    method_density = "kernel",
    method_auc = "trapezoid",
    precision = 2^10,
    extend = TRUE,
    extend_scale = 0.1,
    ...
)
```

## **Arguments**

```
library(bayestestR)

x <- distribution_normal(1000, 2, 0.5)
y <- distribution_normal(1000, 0, 1)

overlap(x, y)
plot(overlap(x, y))</pre>
```

*pd\_to\_p* 71

pd\_to\_p

Convert between Probability of Direction (pd) and p-value.

## **Description**

Enables a conversion between Probability of Direction (pd) and p-value.

### Usage

```
pd_to_p(pd, ...)

## S3 method for class 'numeric'
pd_to_p(pd, direction = "two-sided", verbose = TRUE, ...)

p_to_pd(p, direction = "two-sided", ...)

convert_p_to_pd(p, direction = "two-sided", ...)

convert_pd_to_p(pd, ...)
```

### **Arguments**

pd	A Probability of Direction (pd) value (between 0 and 1). Can also be a data frame with a column named pd, p_direction, or PD, as returned by p_direction(). In this case, the column is converted to p-values and the new data frame is returned.
	Arguments passed to or from other methods.
direction	What type of p-value is requested or provided. Can be "two-sided" (default, two tailed) or "one-sided" (one tailed).
verbose	Toggle off warnings.
р	A p-value.

### **Details**

Conversion is done using the following equation (see Makowski et al., 2019):

```
When direction = "two-sided" p=2\times(1-p_d) When direction = "one-sided" p=1-p_d
```

Note that this conversion is only valid when the lowest possible values of pd is 0.5 - i.e., when the posterior represents continuous parameter space (see p\_direction()). If any pd < 0.5 are detected, they are converted to a p of 1, and a warning is given.

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### Value

A p-value or a data frame with a p-value column.

#### References

Makowski, D., Ben-Shachar, M. S., Chen, S. H. A., and Lüdecke, D. (2019). *Indices of Effect Existence and Significance in the Bayesian Framework*. Frontiers in Psychology 2019;10:2767. doi:10.3389/fpsyg.2019.02767

## **Examples**

```
pd_{to_p(pd = 0.95)}

pd_{to_p(pd = 0.95, direction = "one-sided")}
```

point\_estimate

Point-estimates of posterior distributions

### **Description**

Compute various point-estimates, such as the mean, the median or the MAP, to describe posterior distributions.

```
point_estimate(x, ...)
## S3 method for class 'numeric'
point_estimate(x, centrality = "all", dispersion = FALSE, threshold = 0.1, ...)
## S3 method for class 'data.frame'
point_estimate(
  Х,
  centrality = "all",
  dispersion = FALSE,
  threshold = 0.1,
  rvar_col = NULL,
)
## S3 method for class 'stanreg'
point_estimate(
  centrality = "all",
  dispersion = FALSE,
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
```

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```
"distributional", "auxiliary"),
  parameters = NULL,
)
## S3 method for class 'brmsfit'
point_estimate(
  centrality = "all",
 dispersion = FALSE,
 effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
 parameters = NULL,
)
## S3 method for class 'BFBayesFactor'
point_estimate(x, centrality = "all", dispersion = FALSE, ...)
## S3 method for class 'get_predicted'
point_estimate(
  centrality = "all",
 dispersion = FALSE,
 use_iterations = FALSE,
 verbose = TRUE,
)
```

# Arguments

dispersion

threshold

rvar\_col

x	Vector representing a posterior distribution, or a data frame of such vectors. Can also be a Bayesian model. <b>bayestestR</b> supports a wide range of models (see, for example, methods("hdi")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly resemble the arguments of the .numeric or .data.framemethods.
• • •	Additional arguments to be passed to or from methods.
centrality	The point-estimates (centrality indices) to compute. Character (vector) or list

with one or more of these options: "median", "mean", "MAP" (see map\_estimate()), "trimmed" (which is just mean(x, trim = threshold)), "mode" or "all".

Logical, if TRUE, computes indices of dispersion related to the estimate(s) (SD

and MAD for mean and median, respectively). Dispersion is not available for "MAP" or "mode" centrality indices.

For centrality = "trimmed" (i.e. trimmed mean), indicates the fraction (0 to 0.5) of observations to be trimmed from each end of the vector before the mean is computed.

A single character - the name of an rvar column in the data frame to be processed. See example in p\_direction().

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Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.

Component Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to brms-models.

Parameters Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like lp\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output.

Use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()), the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

#### Note

There is also a plot()-method implemented in the see-package.

Toggle off warnings.

#### References

verbose

Makowski, D., Ben-Shachar, M. S., Chen, S. H. A., and Lüdecke, D. (2019). *Indices of Effect Existence and Significance in the Bayesian Framework*. Frontiers in Psychology 2019;10:2767. doi:10.3389/fpsyg.2019.02767

```
library(bayestestR)
point_estimate(rnorm(1000))
point_estimate(rnorm(1000), centrality = "all", dispersion = TRUE)
point_estimate(rnorm(1000), centrality = c("median", "MAP"))
df <- data.frame(replicate(4, rnorm(100)))</pre>
point_estimate(df, centrality = "all", dispersion = TRUE)
point_estimate(df, centrality = c("median", "MAP"))
# rstanarm models
model <- rstanarm::stan_glm(mpg ~ wt + cyl, data = mtcars)</pre>
point_estimate(model, centrality = "all", dispersion = TRUE)
point_estimate(model, centrality = c("median", "MAP"))
# emmeans estimates
point_estimate(
  emmeans::emtrends(model, ~1, "wt", data = mtcars),
  centrality = c("median", "MAP")
)
```

p\_direction

*Probability of Direction (pd)* 

# **Description**

Compute the **Probability of Direction** (**pd**, also known as the Maximum Probability of Effect - *MPE*). This can be interpreted as the probability that a parameter (described by its posterior distribution) is strictly positive or negative (whichever is the most probable). Although differently expressed, this index is fairly similar (*i.e.*, is strongly correlated) to the frequentist **p-value** (see details).

```
p_direction(x, ...)
pd(x, ...)
## S3 method for class 'numeric'
p_direction(
  Х,
 method = "direct",
 null = 0,
  as_p = FALSE,
  remove_na = TRUE,
)
## S3 method for class 'data.frame'
p_direction(
  х,
  method = "direct",
  null = 0,
  as_p = FALSE,
  remove_na = TRUE,
```

```
rvar_col = NULL,
)
## S3 method for class 'MCMCglmm'
p_direction(
 х,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
)
## S3 method for class 'emmGrid'
p_direction(
 х,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
)
## S3 method for class 'slopes'
p_direction(
 Х,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
)
## S3 method for class 'stanreg'
p_direction(
 Χ,
 effects = c("fixed", "random", "all"),
 component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
)
```

```
## S3 method for class 'brmsfit'
p_direction(
 Х,
 effects = c("fixed", "random", "all"),
 component = c("conditional", "zi", "zero_inflated", "all"),
 parameters = NULL,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
)
## S3 method for class 'BFBayesFactor'
p_direction(
 х,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
)
## S3 method for class 'get_predicted'
p_direction(
 х,
 method = "direct",
 null = 0,
 as_p = FALSE,
 remove_na = TRUE,
 use_iterations = FALSE,
 verbose = TRUE,
)
```

# **Arguments**

X	A vector representing a posterior distribution, a data frame of posterior draws (samples be parameter). Can also be a Bayesian model.
	Currently not used.
method	Can be "direct" or one of methods of estimate_density(), such as "kernel", "logspline" or "KernSmooth". See details.
null	The value considered as a "null" effect. Traditionally 0, but could also be 1 in the case of ratios of change (OR, IRR,).
as_p	If TRUE, the p-direction (pd) values are converted to a frequentist p-value using pd_to_p().
remove_na	Should missing values be removed before computation? Note that Inf (infinity) are <i>not</i> removed.

rvar\_col A single character - the name of an rvar column in the data frame to be processed. See example in p\_direction(). effects Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated. Should results for all parameters, parameters for the conditional model or the component zero-inflated part of the model be returned? May be abbreviated. Only applies to brms-models. parameters Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like lp\_\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output. use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()), the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models). verbose Toggle off warnings.

#### Value

Values between 0.5 and 1 or between 0 and 1 (see above) corresponding to the probability of direction (pd).

## What is the pd?

The Probability of Direction (pd) is an index of effect existence, representing the certainty with which an effect goes in a particular direction (i.e., is positive or negative / has a sign), typically ranging from 0.5 to 1 (but see next section for cases where it can range between 0 and 1). Beyond its simplicity of interpretation, understanding and computation, this index also presents other interesting properties:

- Like other posterior-based indices, *pd* is solely based on the posterior distributions and does not require any additional information from the data or the model (e.g., such as priors, as in the case of Bayes factors).
- It is robust to the scale of both the response variable and the predictors.
- It is strongly correlated with the frequentist p-value, and can thus be used to draw parallels and give some reference to readers non-familiar with Bayesian statistics (Makowski et al., 2019).

## Relationship with the p-value

In most cases, it seems that the pd has a direct correspondence with the frequentist one-sided p-value through the formula (for two-sided p):  $p = 2 \times (1 - p_d)$  Thus, a two-sided p-value of respectively .1, .05, .01 and .001 would correspond approximately to a pd of 95%, 97.5%, 99.5% and 99.95%. See  $pd_{top}()$  for details.

## Possible Range of Values

The largest value pd can take is 1 - the posterior is strictly directional. However, the smallest value pd can take depends on the parameter space represented by the posterior.

**For a continuous parameter space**, exact values of 0 (or any point null value) are not possible, and so 100% of the posterior has *some* sign, some positive, some negative. Therefore, the smallest the *pd* can be is 0.5 - with an equal posterior mass of positive and negative values. Values close to 0.5 *cannot* be used to support the null hypothesis (that the parameter does *not* have a direction) is a similar why to how large p-values cannot be used to support the null hypothesis (see pd\_to\_p(); Makowski et al., 2019).

For a discrete parameter space or a parameter space that is a mixture between discrete and continuous spaces, exact values of 0 (or any point null value) are possible! Therefore, the smallest the pd can be is 0 - with 100% of the posterior mass on 0. Thus values close to 0 can be used to support the null hypothesis (see van den Bergh et al., 2021).

Examples of posteriors representing discrete parameter space:

- When a parameter can only take discrete values.
- When a mixture prior/posterior is used (such as the spike-and-slab prior; see van den Bergh et al., 2021).
- When conducting Bayesian model averaging (e.g., weighted\_posteriors() or brms::posterior\_average).

# Methods of computation

The pd is defined as:

$$p_d = max(Pr(\hat{\theta} < \theta_{null}), Pr(\hat{\theta} > \theta_{null}))$$

The most simple and direct way to compute the pd is to compute the proportion of positive (or larger than null) posterior samples, the proportion of negative (or smaller than null) posterior samples, and take the larger of the two. This "simple" method is the most straightforward, but its precision is directly tied to the number of posterior draws.

The second approach relies on density estimation: It starts by estimating the continuous-smooth density function (for which many methods are available), and then computing the area under the curve (AUC) of the density curve on either side of null and taking the maximum between them. Note the this approach assumes a continuous density function, and so when the posterior represents a (partially) discrete parameter space, only the direct method *must* be used (see above).

# Note

There is also a plot()-method implemented in the see-package.

#### References

- Makowski, D., Ben-Shachar, M. S., Chen, S. A., & Lüdecke, D. (2019). Indices of effect existence and significance in the Bayesian framework. Frontiers in psychology, 10, 2767. doi:10.3389/fpsyg.2019.02767
- van den Bergh, D., Haaf, J. M., Ly, A., Rouder, J. N., & Wagenmakers, E. J. (2021). A cautionary note on estimating effect size. Advances in Methods and Practices in Psychological Science, 4(1). doi:10.1177/2515245921992035

# See Also

pd\_to\_p() to convert between Probability of Direction (pd) and p-value.

```
library(bayestestR)
\# Simulate a posterior distribution of mean 1 and SD 1
posterior <- rnorm(1000, mean = 1, sd = 1)
p_direction(posterior)
p_direction(posterior, method = "kernel")
# Simulate a dataframe of posterior distributions
df <- data.frame(replicate(4, rnorm(100)))</pre>
p_direction(df)
p_direction(df, method = "kernel")
# rstanarm models
# -----
\verb|model <- rstanarm::stan_glm(mpg ~ wt + cyl,
 data = mtcars,
 chains = 2, refresh = 0
p_direction(model)
p_direction(model, method = "kernel")
# emmeans
# -----
p_direction(emmeans::emtrends(model, ~1, "wt", data = mtcars))
# brms models
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
p_direction(model)
p_direction(model, method = "kernel")
# BayesFactor objects
# -----
bf <- BayesFactor::ttestBF(x = rnorm(100, 1, 1))
p_direction(bf)
p_direction(bf, method = "kernel")
# Using "rvar_col"
x \leftarrow data.frame(mu = c(0, 0.5, 1), sigma = c(1, 0.5, 0.25))
x$my_rvar <- posterior::rvar_rng(rnorm, 3, mean = x$mu, sd = x$sigma)</pre>
p_direction(x, rvar_col = "my_rvar")
```

p\_map 81

p\_map

Bayesian p-value based on the density at the Maximum A Posteriori (MAP)

# **Description**

Compute a Bayesian equivalent of the *p*-value, related to the odds that a parameter (described by its posterior distribution) has against the null hypothesis (*h0*) using Mills' (2014, 2017) *Objective Bayesian Hypothesis Testing* framework. It corresponds to the density value at the null (e.g., 0) divided by the density at the Maximum A Posteriori (MAP).

```
p_map(x, ...)
p_pointnull(x, ...)
## S3 method for class 'numeric'
p_map(x, null = 0, precision = 2^10, method = "kernel", ...)
## S3 method for class 'get_predicted'
p_map(
  Х,
  null = 0,
  precision = 2^10,
 method = "kernel",
  use_iterations = FALSE,
  verbose = TRUE,
)
## S3 method for class 'data.frame'
p_map(x, null = 0, precision = 2^10, method = "kernel", rvar_col = NULL, ...)
## S3 method for class 'stanreg'
p_map(
  х,
  null = 0,
  precision = 2^10,
  method = "kernel",
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
)
```

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```
## S3 method for class 'brmsfit'
p_map(
  Х,
  null = 0,
  precision = 2^10,
 method = "kernel",
 effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
 parameters = NULL.
)
```

## **Arguments**

X	Vector representing a posterior distribution, or a data frame of such vectors. Can also be a Bayesian model. <b>bayestestR</b> supports a wide range of models (see, for example, methods("hdi")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly resemble the arguments of the .numeric or .data.framemethods.
	Currently not used.
null	The value considered as a "null" effect. Traditionally 0, but could also be 1 in the case of ratios of change (OR, IRR,).
precision	Number of points of density data. See the n parameter in density.

Density estimation method. Can be "kernel" (default), "logspline" or "KernSmooth". method

use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()),

the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

Toggle off warnings. verbose

A single character - the name of an rvar column in the data frame to be prorvar\_col

cessed. See example in p\_direction().

Should results for fixed effects, random effects or both be returned? Only applies effects

to mixed models. May be abbreviated.

Should results for all parameters, parameters for the conditional model or the component

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

Regular expression pattern that describes the parameters that should be returned. parameters

> Meta-parameters (like 1p\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

## **Details**

Note that this method is sensitive to the density estimation method (see the section in the examples below).

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## **Strengths and Limitations:**

Strengths: Straightforward computation. Objective property of the posterior distribution.

**Limitations:** Limited information favoring the null hypothesis. Relates on density approximation. Indirect relationship between mathematical definition and interpretation. Only suitable for weak / very diffused priors.

#### References

- Makowski D, Ben-Shachar MS, Chen SHA, Lüdecke D (2019) Indices of Effect Existence and Significance in the Bayesian Framework. Frontiers in Psychology 2019;10:2767. doi:10.3389/ fpsyg.2019.02767
- Mills, J. A. (2018). Objective Bayesian Precise Hypothesis Testing. University of Cincinnati.

#### See Also

Jeff Mill's talk

```
library(bayestestR)
p_map(rnorm(1000, 0, 1))
p_map(rnorm(1000, 10, 1))
model <- suppressWarnings(</pre>
  rstanarm::stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
p_map(model)
p_map(suppressWarnings(
  emmeans::emtrends(model, ~1, "wt", data = mtcars)
))
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
p_map(model)
bf <- BayesFactor::ttestBF(x = rnorm(100, 1, 1))
p_map(bf)
# Robustness to density estimation method
set.seed(333)
data <- data.frame()</pre>
for (iteration in 1:250) {
  x <- rnorm(1000, 1, 1)
  result <- data.frame(</pre>
    Kernel = as.numeric(p_map(x, method = "kernel")),
    KernSmooth = as.numeric(p_map(x, method = "KernSmooth")),
    logspline = as.numeric(p_map(x, method = "logspline"))
  data <- rbind(data, result)</pre>
```

p\_rope

```
}
data$KernSmooth <- data$Kernel - data$KernSmooth
data$logspline <- data$Kernel - data$logspline

summary(data$KernSmooth)
summary(data$logspline)
boxplot(data[c("KernSmooth", "logspline")])</pre>
```

p\_rope

Probability of being in the ROPE

## **Description**

Compute the proportion of the whole posterior distribution that doesn't lie within a region of practical equivalence (ROPE). It is equivalent to running rope(..., ci = 1).

```
p_rope(x, ...)
## S3 method for class 'numeric'
p_rope(x, range = "default", verbose = TRUE, ...)
## S3 method for class 'data.frame'
p_rope(x, range = "default", rvar_col = NULL, verbose = TRUE, ...)
## S3 method for class 'stanreg'
p_rope(
  range = "default";
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
  verbose = TRUE,
## S3 method for class 'brmsfit'
p_rope(
  Х,
  range = "default",
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL,
  verbose = TRUE,
```

*p\_rope* 85

```
)
```

# **Arguments**

x Vector representing a posterior distribution. Can also be a stanneg or brmsfit

... Currently not used.

range ROPE's lower and higher bounds. Should be "default" or depending on the number of outcome variables a vector or a list. For models with one response, range can be:

- a vector of length two (e.g., c(-0.1, 0.1)),
- a list of numeric vector of the same length as numbers of parameters (see 'Examples').
- a list of *named* numeric vectors, where names correspond to parameter names. In this case, all parameters that have no matching name in range will be set to "default".

In multivariate models, range should be a list with another list (one for each response variable) of numeric vectors. Vector names should correspond to the name of the response variables. If "default" and input is a vector, the range is set to c(-0.1, 0.1). If "default" and input is a Bayesian model, rope\_range() is used. See 'Examples'.

verbose Toggle off warnings.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like lp\_\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

```
library(bayestestR) p\_rope(x = rnorm(1000, 0, 0.01), range = c(-0.1, 0.1)) p\_rope(x = mtcars, range = c(-0.1, 0.1))
```

p\_significance

p\_significance

Practical Significance (ps)

# **Description**

Compute the probability of **Practical Significance** (ps), which can be conceptualized as a unidirectional equivalence test. It returns the probability that effect is above a given threshold corresponding to a negligible effect in the median's direction. Mathematically, it is defined as the proportion of the posterior distribution of the median sign above the threshold.

```
p_significance(x, ...)
## S3 method for class 'numeric'
p_significance(x, threshold = "default", ...)
## S3 method for class 'get_predicted'
p_significance(
  х,
  threshold = "default",
  use_iterations = FALSE,
  verbose = TRUE,
)
## S3 method for class 'data.frame'
p_significance(x, threshold = "default", rvar_col = NULL, ...)
## S3 method for class 'stanreg'
p_significance(
  threshold = "default",
  effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
  parameters = NULL,
  verbose = TRUE,
)
## S3 method for class 'brmsfit'
p_significance(
  threshold = "default",
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
```

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```
parameters = NULL,
verbose = TRUE,
...
)
```

#### **Arguments**

x Vector representing a posterior distribution. Can also be a stanneg or brmsfit

model.

... Currently not used.

threshold The threshold value that separates significant from negligible effect, which can have following possible values:

- "default", in which case the range is set to 0.1 if input is a vector, and based on rope\_range() if a (Bayesian) model is provided.
- a single numeric value (e.g., 0.1), which is used as range around zero (i.e. the threshold range is set to -0.1 and 0.1, i.e. reflects a symmetric interval)
- a numeric vector of length two (e.g., c(-0.2, 0.1)), useful for asymmetric intervals
- a list of numeric vectors, where each vector corresponds to a parameter
- a list of *named* numeric vectors, where names correspond to parameter names. In this case, all parameters that have no matching name in threshold will be set to "default".

use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()),

the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

verbose Toggle off warnings.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like  $lp\_$  or  $prior\_$ ) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

#### Details

p\_significance() returns the proportion of a probability distribution (x) that is outside a certain range (the negligible effect, or ROPE, see argument threshold). If there are values of the distribution both below and above the ROPE, p\_significance() returns the higher probability of a value being outside the ROPE. Typically, this value should be larger than 0.5 to indicate practical significance. However, if the range of the negligible effect is rather large compared to the range of the probability distribution x, p\_significance() will be less than 0.5, which indicates no clear practical significance.

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## Value

Values between 0 and 1 corresponding to the probability of practical significance (ps).

#### Note

There is also a plot()-method implemented in the see-package.

# **Examples**

```
library(bayestestR)
# Simulate a posterior distribution of mean 1 and SD 1
posterior <- rnorm(1000, mean = 1, sd = 1)
p_significance(posterior)
# Simulate a dataframe of posterior distributions
# -----
df <- data.frame(replicate(4, rnorm(100)))</pre>
p_significance(df)
# rstanarm models
# -----
model <- rstanarm::stan_glm(mpg \sim wt + cyl,
 data = mtcars,
 chains = 2, refresh = 0
)
p_significance(model)
# multiple thresholds - asymmetric, symmetric, default
p_significance(model, threshold = list(c(-10, 5), 0.2, "default"))
# named thresholds
p_significance(model, threshold = list(wt = 0.2, `(Intercept)` = c(-10, 5)))
```

p\_to\_bf

Convert p-values to (pseudo) Bayes Factors

# Description

Convert p-values to (pseudo) Bayes Factors. This transformation has been suggested by Wagenmakers (2022), but is based on a vast amount of assumptions. It might therefore be not reliable. Use at your own risks. For more accurate approximate Bayes factors, use bic\_to\_bf() instead.

```
p_to_bf(x, ...)
## S3 method for class 'numeric'
```

p\_to\_bf

```
p_to_bf(x, log = FALSE, n_obs = NULL, ...)
## Default S3 method:
p_to_bf(x, log = FALSE, ...)
```

## **Arguments**

A (frequentist) model object, or a (numeric) vector of p-values.
 Other arguments to be passed (not used for now).
 Wether to return log Bayes Factors. Note: The print() method always shows BF - the "log\_BF" column is only accessible from the returned data frame.
 Number of observations. Either length 1, or same length as p.

#### Value

A data frame with the p-values and pseudo-Bayes factors (against the null).

#### References

• Wagenmakers, E.J. (2022). Approximate objective Bayes factors from p-values and sample size: The 3p(sqrt(n)) rule. Preprint available on ArXiv: https://psyarxiv.com/egydq

#### See Also

bic\_to\_bf() for more accurate approximate Bayes factors.

```
data(iris)
model <- lm(Petal.Length ~ Sepal.Length + Species, data = iris)</pre>
p_to_bf(model)
# Examples that demonstrate comparison between
# BIC-approximated and pseudo BF
m0 <- lm(mpg ~ 1, mtcars)</pre>
m1 <- lm(mpg \sim am, mtcars)
m2 <- lm(mpg ~ factor(cyl), mtcars)</pre>
# In this first example, BIC-approximated BF and
# pseudo-BF based on p-values are close...
# BIC-approximated BF, m1 against null model
bic_to_bf(BIC(m1), denominator = BIC(m0))
# pseudo-BF based on p-values - dropping intercept
p_to_bf(m1)[-1, ]
# The second example shows that results from pseudo-BF are less accurate
# and should be handled wit caution!
bic_to_bf(BIC(m2), denominator = BIC(m0))
```

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```
p_to_bf(anova(m2), n_obs = nrow(mtcars))
```

reshape\_iterations

Reshape estimations with multiple iterations (draws) to long format

# **Description**

Reshape a wide data.frame of iterations (such as posterior draws or bootsrapped samples) as columns to long format. Instead of having all iterations as columns (e.g., iter\_1, iter\_2, ...), will return 3 columns with the \\*\_index (the previous index of the row), the \\*\_group (the iteration number) and the \\*\_value (the value of said iteration).

# Usage

```
reshape_iterations(x, prefix = c("draw", "iter", "iteration", "sim"))
reshape_draws(x, prefix = c("draw", "iter", "iteration", "sim"))
```

# **Arguments**

x A data.frame containing posterior draws obtained from estimate\_response or estimate\_link.

prefix The prefix of the draws (for instance, "iter\_" for columns named as iter\_1, iter\_2, iter\_3).

If more than one are provided, will search for the first one that matches.

#### Value

Data frame of reshaped draws in long format.

```
if (require("rstanarm")) {
  model <- stan_glm(mpg ~ am, data = mtcars, refresh = 0)
  draws <- insight::get_predicted(model)
  long_format <- reshape_iterations(draws)
  head(long_format)
}</pre>
```

rope

Region of Practical Equivalence (ROPE)

# **Description**

Compute the proportion of the HDI (default to the 89% HDI) of a posterior distribution that lies within a region of practical equivalence.

```
rope(x, ...)
## S3 method for class 'numeric'
rope(x, range = "default", ci = 0.95, ci_method = "ETI", verbose = TRUE, ...)
## S3 method for class 'data.frame'
rope(
 х,
 range = "default",
 ci = 0.95,
 ci_method = "ETI",
  rvar_col = NULL,
  verbose = TRUE,
)
## S3 method for class 'stanreg'
rope(
 Х,
 range = "default",
 ci = 0.95,
 ci_method = "ETI",
 effects = c("fixed", "random", "all"),
  component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
 parameters = NULL,
 verbose = TRUE,
)
## S3 method for class 'brmsfit'
rope(
 х,
  range = "default",
 ci = 0.95,
  ci_method = "ETI",
 effects = c("fixed", "random", "all"),
```

```
component = c("conditional", "zi", "zero_inflated", "all"),
parameters = NULL,
verbose = TRUE,
...
)
```

#### **Arguments**

x Vector representing a posterior distribution. Can also be a stanneg or brmsfit model.

.. Currently not used.

range ROPE's lower and higher bounds. Should be "default" or depending on the number of outcome variables a vector or a list. For models with one response, range can be:

• a vector of length two (e.g., c(-0.1, 0.1)),

- a list of numeric vector of the same length as numbers of parameters (see 'Examples').
- a list of *named* numeric vectors, where names correspond to parameter names. In this case, all parameters that have no matching name in range will be set to "default".

In multivariate models, range should be a list with another list (one for each response variable) of numeric vectors. Vector names should correspond to the name of the response variables. If "default" and input is a vector, the range is set to c(-0.1, 0.1). If "default" and input is a Bayesian model, rope\_range() is used. See 'Examples'.

ci The Credible Interval (CI) probability, corresponding to the proportion of HDI,

to use for the percentage in ROPE.

ci\_method The type of interval to use to quantify the percentage in ROPE. Can be 'HDI'

(default) or 'ETI'. See ci().

verbose Toggle off warnings.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to **brms**-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like  $lp\_$  or  $prior\_$ ) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

## **ROPE**

Statistically, the probability of a posterior distribution of being different from 0 does not make much sense (the probability of a single value null hypothesis in a continuous distribution is 0). Therefore,

the idea underlining ROPE is to let the user define an area around the null value enclosing values that are *equivalent to the null* value for practical purposes (*Kruschke 2010, 2011, 2014*).

Kruschke (2018) suggests that such null value could be set, by default, to the -0.1 to 0.1 range of a standardized parameter (negligible effect size according to Cohen, 1988). This could be generalized: For instance, for linear models, the ROPE could be set as 0 +/- .1 \* sd(y). This ROPE range can be automatically computed for models using the rope\_range() function.

Kruschke (2010, 2011, 2014) suggests using the proportion of the 95% (or 89%, considered more stable) HDI that falls within the ROPE as an index for "null-hypothesis" testing (as understood under the Bayesian framework, see equivalence\_test()).

## Sensitivity to parameter's scale

It is important to consider the unit (i.e., the scale) of the predictors when using an index based on the ROPE, as the correct interpretation of the ROPE as representing a region of practical equivalence to zero is dependent on the scale of the predictors. Indeed, the percentage in ROPE depend on the unit of its parameter. In other words, as the ROPE represents a fixed portion of the response's scale, its proximity with a coefficient depends on the scale of the coefficient itself.

## **Multicollinearity - Non-independent covariates**

When parameters show strong correlations, i.e. when covariates are not independent, the joint parameter distributions may shift towards or away from the ROPE. Collinearity invalidates ROPE and hypothesis testing based on univariate marginals, as the probabilities are conditional on independence. Most problematic are parameters that only have partial overlap with the ROPE region. In case of collinearity, the (joint) distributions of these parameters may either get an increased or decreased ROPE, which means that inferences based on rope() are inappropriate (*Kruschke 2014*, 340f).

rope() performs a simple check for pairwise correlations between parameters, but as there can be collinearity between more than two variables, a first step to check the assumptions of this hypothesis testing is to look at different pair plots. An even more sophisticated check is the projection predictive variable selection (*Piironen and Vehtari 2017*).

# **Strengths and Limitations**

**Strengths:** Provides information related to the practical relevance of the effects.

**Limitations:** A ROPE range needs to be arbitrarily defined. Sensitive to the scale (the unit) of the predictors. Not sensitive to highly significant effects.

#### Note

There is also a plot()-method implemented in the see-package.

#### References

- Cohen, J. (1988). Statistical power analysis for the behavioural sciences.
- Kruschke, J. K. (2010). What to believe: Bayesian methods for data analysis. Trends in cognitive sciences, 14(7), 293-300. doi:10.1016/j.tics.2010.05.001.

 Kruschke, J. K. (2011). Bayesian assessment of null values via parameter estimation and model comparison. Perspectives on Psychological Science, 6(3), 299-312. doi:10.1177/ 1745691611406925.

- Kruschke, J. K. (2014). Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan. Academic Press. doi:10.1177/2515245918771304.
- Kruschke, J. K. (2018). Rejecting or accepting parameter values in Bayesian estimation. Advances in Methods and Practices in Psychological Science, 1(2), 270-280. doi:10.1177/2515245918771304.
- Makowski D, Ben-Shachar MS, Chen SHA, Lüdecke D (2019) Indices of Effect Existence and Significance in the Bayesian Framework. Frontiers in Psychology 2019;10:2767. doi:10.3389/ fpsyg.2019.02767
- Piironen, J., & Vehtari, A. (2017). Comparison of Bayesian predictive methods for model selection. Statistics and Computing, 27(3), 711–735. doi:10.1007/s112220169649y

```
library(bayestestR)
rope(x = rnorm(1000, 0, 0.01), range = c(-0.1, 0.1))
rope(x = rnorm(1000, 0, 1), range = c(-0.1, 0.1))
rope(x = rnorm(1000, 1, 0.01), range = c(-0.1, 0.1))
rope(x = rnorm(1000, 1, 1), ci = c(0.90, 0.95))
library(rstanarm)
model <- suppressWarnings(</pre>
  stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
rope(model)
rope(model, ci = c(0.90, 0.95))
# multiple ROPE ranges
rope(model, range = list(c(-10, 5), c(-0.2, 0.2), "default"))
# named ROPE ranges
rope(model, range = list(gear = c(-3, 2), wt = c(-0.2, 0.2)))
library(emmeans)
rope(emtrends(model, ~1, "wt"), ci = c(0.90, 0.95))
library(brms)
model <- brm(mpg ~ wt + cyl, data = mtcars, refresh = 0)
rope(model)
rope(model, ci = c(0.90, 0.95))
library(brms)
model <- brm(</pre>
  bf(mvbind(mpg, disp) ~ wt + cyl) + set_rescor(rescor = TRUE),
  data = mtcars,
  refresh = 0
)
```

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```
rope(model)
rope(model, ci = c(0.90, 0.95))

# different ROPE ranges for model parameters. For each response, a named
# list (with the name of the response variable) is required as list-element
# for the `range` argument.
rope(
    model,
    range = list(
        mpg = list(b_mpg_wt = c(-1, 1), b_mpg_cyl = c(-2, 2)),
        disp = list(b_disp_wt = c(-5, 5), b_disp_cyl = c(-4, 4))
    )
)

library(BayesFactor)
bf <- ttestBF(x = rnorm(100, 1, 1))
rope(bf)
rope(bf, ci = c(0.90, 0.95))</pre>
```

rope\_range

Find Default Equivalence (ROPE) Region Bounds

# Description

This function attempts at automatically finding suitable "default" values for the Region Of Practical Equivalence (ROPE).

#### Usage

```
rope_range(x, ...)
## Default S3 method:
rope_range(x, verbose = TRUE, ...)
```

# **Arguments**

x A stanreg, brmsfit or BFBayesFactor object, or a frequentist regression model.
... Currently not used.

verbose Toggle warnings.

#### **Details**

*Kruschke* (2018) suggests that the region of practical equivalence could be set, by default, to a range from -0.1 to 0.1 of a standardized parameter (negligible effect size according to *Cohen*, 1988).

• For **linear models (lm)**, this can be generalised to  $[-0.1 * SD_y, 0.1 * SD_y]$ .

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• For **logistic models**, the parameters expressed in log odds ratio can be converted to standardized difference through the formula  $\pi/\sqrt{3}$ , resulting in a range of -0.18 to 0.18.

- For other models with **binary outcome**, it is strongly recommended to manually specify the rope argument. Currently, the same default is applied that for logistic models.
- For models from **count data**, the residual variance is used. This is a rather experimental threshold and is probably often similar to -0.1, 0.1, but should be used with care!
- For **t-tests**, the standard deviation of the response is used, similarly to linear models (see above).
- For **correlations**, -0.05, 0.05 is used, i.e., half the value of a negligible correlation as suggested by Cohen's (1988) rules of thumb.
- For all other models, -0.1, 0.1 is used to determine the ROPE limits, but it is strongly advised to specify it manually.

#### References

Kruschke, J. K. (2018). Rejecting or accepting parameter values in Bayesian estimation. Advances in Methods and Practices in Psychological Science, 1(2), 270-280. doi:10.1177/2515245918771304.

```
model <- suppressWarnings(rstanarm::stan_glm(</pre>
  mpg ~ wt + gear,
  data = mtcars,
  chains = 2,
  iter = 200,
  refresh = 0
))
rope_range(model)
model <- suppressWarnings(</pre>
  rstanarm::stan_glm(vs ~ mpg, data = mtcars, family = "binomial", refresh = 0)
rope_range(model)
model <- brms::brm(mpg ~ wt + cyl, data = mtcars)</pre>
rope_range(model)
model <- BayesFactor::ttestBF(mtcars[mtcars$vs == 1, "mpg"], mtcars[mtcars$vs == 0, "mpg"])</pre>
rope_range(model)
model <- lmBF(mpg ~ vs, data = mtcars)</pre>
rope_range(model)
```

sensitivity\_to\_prior 97

# **Description**

Computes the sensitivity to priors specification. This represents the proportion of change in some indices when the model is fitted with an antagonistic prior (a prior of same shape located on the opposite of the effect).

# Usage

```
sensitivity_to_prior(model, ...)
## S3 method for class 'stanreg'
sensitivity_to_prior(model, index = "Median", magnitude = 10, ...)
```

# **Arguments**

model A Bayesian model (stanreg or brmsfit).
... Arguments passed to or from other methods.

index The indices from which to compute the sensitivity. Can be one or multiple names

of the columns returned by describe\_posterior. The case is important here

(e.g., write 'Median' instead of 'median').

magnitude This represent the magnitude by which to shift the antagonistic prior (to test

the sensitivity). For instance, a magnitude of 10 (default) means that the mode wil be updated with a prior located at 10 standard deviations from its original

location.

## See Also

DescTools

```
library(bayestestR)

# rstanarm models
# ------
model <- rstanarm::stan_glm(mpg ~ wt, data = mtcars)
sensitivity_to_prior(model)

model <- rstanarm::stan_glm(mpg ~ wt + cyl, data = mtcars)
sensitivity_to_prior(model, index = c("Median", "MAP"))</pre>
```

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sexit

Sequential Effect eXistence and sIgnificance Testing (SEXIT)

## **Description**

The SEXIT is a new framework to describe Bayesian effects, guiding which indices to use. Accordingly, the sexit() function returns the minimal (and optimal) required information to describe models' parameters under a Bayesian framework. It includes the following indices:

- Centrality: the median of the posterior distribution. In probabilistic terms, there is 50% of probability that the effect is higher and lower. See point\_estimate().
- Uncertainty: the 95% Highest Density Interval (HDI). In probabilistic terms, there is 95% of probability that the effect is within this confidence interval. See ci().
- Existence: The probability of direction allows to quantify the certainty by which an effect is positive or negative. It is a critical index to show that an effect of some manipulation is not harmful (for instance in clinical studies) or to assess the direction of a link. See p\_direction().
- Significance: Once existence is demonstrated with high certainty, we can assess whether the effect is of sufficient size to be considered as significant (i.e., not negligible). This is a useful index to determine which effects are actually important and worthy of discussion in a given process. See p\_significance().
- Size: Finally, this index gives an idea about the strength of an effect. However, beware, as studies have shown that a big effect size can be also suggestive of low statistical power (see details section).

## Usage

```
sexit(x, significant = "default", large = "default", ci = 0.95, ...)
```

#### **Arguments**

A vector representing a posterior distribution, a data frame of posterior draws (samples be parameter). Can also be a Bayesian model.

significant, large

The threshold values to use for significant and large probabilities. If left to 'default', will be selected through sexit\_thresholds(). See the details section below.

value or vector of probability of the (credible) interval - CI (between 0 and 1) to be estimated. Default to .95 (95%).

... Currently not used.

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#### **Details**

**Rationale:** The assessment of "significance" (in its broadest meaning) is a pervasive issue in science, and its historical index, the p-value, has been strongly criticized and deemed to have played an important role in the replicability crisis. In reaction, more and more scientists have tuned to Bayesian methods, offering an alternative set of tools to answer their questions. However, the Bayesian framework offers a wide variety of possible indices related to "significance", and the debate has been raging about which index is the best, and which one to report.

This situation can lead to the mindless reporting of all possible indices (with the hopes that with that the reader will be satisfied), but often without having the writer understanding and interpreting them. It is indeed complicated to juggle between many indices with complicated definitions and subtle differences.

SEXIT aims at offering a practical framework for Bayesian effects reporting, in which the focus is put on intuitiveness, explicitness and usefulness of the indices' interpretation. To that end, we suggest a system of description of parameters that would be intuitive, easy to learn and apply, mathematically accurate and useful for taking decision.

Once the thresholds for significance (i.e., the ROPE) and the one for a "large" effect are explicitly defined, the SEXIT framework does not make any interpretation, i.e., it does not label the effects, but just sequentially gives 3 probabilities (of direction, of significance and of being large, respectively) as-is on top of the characteristics of the posterior (using the median and HDI for centrality and uncertainty description). Thus, it provides a lot of information about the posterior distribution (through the mass of different 'sections' of the posterior) in a clear and meaningful way.

**Threshold selection:** One of the most important thing about the SEXIT framework is that it relies on two "arbitrary" thresholds (i.e., that have no absolute meaning). They are the ones related to effect size (an inherently subjective notion), namely the thresholds for significant and large effects. They are set, by default, to 0.05 and 0.3 of the standard deviation of the outcome variable (tiny and large effect sizes for correlations according to Funder and Ozer, 2019). However, these defaults were chosen by lack of a better option, and might not be adapted to your case. Thus, they are to be handled with care, and the chosen thresholds should always be explicitly reported and justified.

- For **linear models (lm)**, this can be generalised to  $[0.05*SD_y]$  and  $[0.3*SD_y]$  for significant and large effects, respectively.
- For **logistic models**, the parameters expressed in log odds ratio can be converted to standardized difference through the formula  $\pi/\sqrt{3}$ , resulting a threshold of 0.09 and 0.54.
- For other models with **binary outcome**, it is strongly recommended to manually specify the rope argument. Currently, the same default is applied that for logistic models.
- For models from **count data**, the residual variance is used. This is a rather experimental threshold and is probably often similar to 0.05 and 0.3, but should be used with care!
- For **t-tests**, the standard deviation of the response is used, similarly to linear models (see above).
- For **correlations**, 0.05 and 0.3 are used.
- For all other models, 0.05 and 0.3 are used, but it is strongly advised to specify it manually.

**Examples:** The three values for existence, significance and size provide a useful description of the posterior distribution of the effects. Some possible scenarios include:

• The probability of existence is low, but the probability of being large is high: it suggests that the posterior is very wide (covering large territories on both side of 0). The statistical power might be too low, which should warrant any confident conclusion.

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• The probability of existence and significance is high, but the probability of being large is very small: it suggests that the effect is, with high confidence, not large (the posterior is mostly contained between the significance and the large thresholds).

• The 3 indices are very low: this suggests that the effect is null with high confidence (the posterior is closely centred around 0).

#### Value

A dataframe and text as attribute.

#### References

- Makowski, D., Ben-Shachar, M. S., & Lüdecke, D. (2019). bayestestR: Describing Effects and their Uncertainty, Existence and Significance within the Bayesian Framework. Journal of Open Source Software, 4(40), 1541. doi:10.21105/joss.01541
- Makowski D, Ben-Shachar MS, Chen SHA, Lüdecke D (2019) Indices of Effect Existence and Significance in the Bayesian Framework. Frontiers in Psychology 2019;10:2767. doi:10.3389/ fpsyg.2019.02767

#### **Examples**

sexit\_thresholds

Find Effect Size Thresholds

## **Description**

This function attempts at automatically finding suitable default values for a "significant" (i.e., non-negligible) and "large" effect. This is to be used with care, and the chosen threshold should always be explicitly reported and justified. See the detail section in sexit() for more information.

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## Usage

```
sexit_thresholds(x, ...)
```

## **Arguments**

x Vector representing a posterior distribution. Can also be a stanneg or brmsfit model.

... Currently not used.

## References

Kruschke, J. K. (2018). Rejecting or accepting parameter values in Bayesian estimation. Advances in Methods and Practices in Psychological Science, 1(2), 270-280. doi:10.1177/2515245918771304.

```
sexit_thresholds(rnorm(1000))
if (require("rstanarm")) {
  model <- suppressWarnings(stan_glm(</pre>
    mpg ~ wt + gear,
    data = mtcars,
    chains = 2,
    iter = 200,
    refresh = 0
  sexit_thresholds(model)
  model <- suppressWarnings(</pre>
    stan_glm(vs ~ mpg, data = mtcars, family = "binomial", refresh = 0)
  )
  sexit_thresholds(model)
}
if (require("brms")) {
  model <- brm(mpg ~ wt + cyl, data = mtcars)</pre>
  sexit_thresholds(model)
}
if (require("BayesFactor")) {
  bf <- ttestBF(x = rnorm(100, 1, 1))
  sexit_thresholds(bf)
}
```

# **Description**

A support interval contains only the values of the parameter that predict the observed data better than average, by some degree k; these are values of the parameter that are associated with an updating factor greater or equal than k. From the perspective of the Savage-Dickey Bayes factor, testing against a point null hypothesis for any value within the support interval will yield a Bayes factor smaller than 1/k.

si

```
si(posterior, ...)
## S3 method for class 'numeric'
si(posterior, prior = NULL, BF = 1, verbose = TRUE, ...)
## S3 method for class 'stanreg'
si(
  posterior,
 prior = NULL,
 BF = 1,
 verbose = TRUE,
  effects = c("fixed", "random", "all"),
 component = c("location", "conditional", "all", "smooth_terms", "sigma", "auxiliary",
    "distributional"),
 parameters = NULL,
)
## S3 method for class 'brmsfit'
si(
  posterior,
 prior = NULL,
 BF = 1,
 verbose = TRUE,
  effects = c("fixed", "random", "all"),
 component = c("location", "conditional", "all", "smooth_terms", "sigma", "auxiliary",
    "distributional"),
  parameters = NULL,
)
## S3 method for class 'blavaan'
 posterior,
```

```
prior = NULL,
      BF = 1,
      verbose = TRUE,
      effects = c("fixed", "random", "all"),
     component = c("location", "conditional", "all", "smooth_terms", "sigma", "auxiliary",
         "distributional"),
      parameters = NULL,
    )
    ## S3 method for class 'emmGrid'
    si(posterior, prior = NULL, BF = 1, verbose = TRUE, ...)
    ## S3 method for class 'get_predicted'
    si(
      posterior,
      prior = NULL,
      BF = 1,
      use_iterations = FALSE,
      verbose = TRUE,
    )
    ## S3 method for class 'data.frame'
    si(posterior, prior = NULL, BF = 1, rvar_col = NULL, verbose = TRUE, ...)
Arguments
                      A numerical vector, stanneg / brmsfit object, emmGrid or a data frame - rep-
    posterior
                      resenting a posterior distribution(s) from (see 'Details').
                      Arguments passed to and from other methods. (Can be used to pass arguments
    . . .
                      to internal logspline::logspline().)
                      An object representing a prior distribution (see 'Details').
    prior
    BF
                     The amount of support required to be included in the support interval.
    verbose
                     Toggle off warnings.
    effects
                      Should results for fixed effects, random effects or both be returned? Only applies
                      to mixed models. May be abbreviated.
                      Should results for all parameters, parameters for the conditional model or the
    component
                      zero-inflated part of the model be returned? May be abbreviated. Only applies
                     to brms-models.
    parameters
                      Regular expression pattern that describes the parameters that should be returned.
                      Meta-parameters (like lp__ or prior_) are filtered by default, so only param-
                     eters that typically appear in the summary() are returned. Use parameters to
                      select specific parameters for the output.
    use_iterations Logical, if TRUE and x is a get_predicted object, (returned by insight::get_predicted()),
```

the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

rvar\_col

A single character - the name of an rvar column in the data frame to be processed. See example in p\_direction().

## **Details**

For more info, in particular on specifying correct priors for factors with more than 2 levels, see the Bayes factors vignette.

This method is used to compute support intervals based on prior and posterior distributions. For the computation of support intervals, the model priors must be proper priors (at the very least they should be *not flat*, and it is preferable that they be *informative* - note that by default, brms::brm() uses flat priors for fixed-effects; see example below).

#### Value

A data frame containing the lower and upper bounds of the SI.

Note that if the level of requested support is higher than observed in the data, the interval will be [NA,NA].

# Choosing a value of BF

The choice of BF (the level of support) depends on what we want our interval to represent:

- A BF = 1 contains values whose credibility is not decreased by observing the data.
- A BF > 1 contains values who received more impressive support from the data.
- A BF < 1 contains values whose credibility has *not* been impressively decreased by observing the data. Testing against values outside this interval will produce a Bayes factor larger than 1/BF in support of the alternative. E.g., if an SI (BF = 1/3) excludes 0, the Bayes factor against the point-null will be larger than 3.

# Setting the correct prior

For the computation of Bayes factors, the model priors must be proper priors (at the very least they should be *not flat*, and it is preferable that they be *informative*); As the priors for the alternative get wider, the likelihood of the null value(s) increases, to the extreme that for completely flat priors the null is infinitely more favorable than the alternative (this is called *the Jeffreys-Lindley-Bartlett paradox*). Thus, you should only ever try (or want) to compute a Bayes factor when you have an informed prior.

(Note that by default, brms::brm() uses flat priors for fixed-effects; See example below.)

It is important to provide the correct prior for meaningful results, to match the posterior-type input:

- A numeric vector prior should also be a *numeric vector*, representing the prior-estimate.
- A data frame prior should also be a *data frame*, representing the prior-estimates, in matching column order.
  - If rvar\_col is specified, prior should be the name of an rvar column that represents the prior-estimates.

- Supported Bayesian model (stanreg, brmsfit, etc.)
  - prior should be a model an equivalent model with MCMC samples from the priors only.
     See unupdate().
  - If prior is set to NULL, unupdate() is called internally (not supported for brmsfit\_multiple model).
- Output from a {marginaleffects} function prior should also be an equivalent output from a {marginaleffects} function based on a prior-model (See unupdate()).
- Output from an {emmeans} function
  - prior should also be an equivalent output from an {emmeans} function based on a priormodel (See unupdate()).
  - prior can also be the original (posterior) model, in which case the function will try to "unupdate" the estimates (not supported if the estimates have undergone any transformations – "log", "response", etc. – or any regriding).

#### Note

There is also a plot()-method implemented in the see-package.

#### References

Wagenmakers, E., Gronau, Q. F., Dablander, F., & Etz, A. (2018, November 22). The Support Interval. doi:10.31234/osf.io/zwnxb

#### See Also

```
Other ci: bci(), ci(), eti(), hdi(), spi()
```

```
library(bayestestR)
prior <- distribution_normal(1000, mean = 0, sd = 1)</pre>
posterior <- distribution_normal(1000, mean = 0.5, sd = 0.3)</pre>
si(posterior, prior, verbose = FALSE)
# rstanarm models
# -----
library(rstanarm)
contrasts(sleep$group) <- contr.equalprior_pairs # see vignette</pre>
stan_model <- stan_lmer(extra ~ group + (1 | ID), data = sleep)</pre>
si(stan_model, verbose = FALSE)
si(stan_model, BF = 3, verbose = FALSE)
# emmGrid objects
# -----
library(emmeans)
group_diff <- pairs(emmeans(stan_model, ~group))</pre>
si(group_diff, prior = stan_model, verbose = FALSE)
```

simulate\_correlation

```
# brms models
# ------
library(brms)
contrasts(sleep$group) <- contr.equalprior_pairs # see vingette
my_custom_priors <-
    set_prior("student_t(3, 0, 1)", class = "b") +
    set_prior("student_t(3, 0, 1)", class = "sd", group = "ID")

brms_model <- suppressWarnings(brm(extra ~ group + (1 | ID),
    data = sleep,
    prior = my_custom_priors,
    refresh = 0
))
si(brms_model, verbose = FALSE)</pre>
```

 $simulate\_correlation$  Data Simulation

# **Description**

Simulate data with specific characteristics.

# Usage

```
simulate\_correlation(n = 100, r = 0.5, mean = 0, sd = 1, names = NULL, ...)
simulate\_ttest(n = 100, d = 0.5, names = NULL, ...)
simulate\_difference(n = 100, d = 0.5, names = NULL, ...)
```

# **Arguments**

n	The number of observations to be generated.
r	A value or vector corresponding to the desired correlation coefficients.
mean	A value or vector corresponding to the mean of the variables.
sd	A value or vector corresponding to the SD of the variables.
names	A character vector of desired variable names.
	Arguments passed to or from other methods.
d	A value or vector corresponding to the desired difference between the groups

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```
# Correlation -----
data <- simulate_correlation(r = 0.5)</pre>
plot(data$V1, data$V2)
cor.test(data$V1, data$V2)
summary(lm(V2 \sim V1, data = data))
# Specify mean and SD
data <- simulate_correlation(r = 0.5, n = 50, mean = c(0, 1), sd = c(0.7, 1.7))
cor.test(data$V1, data$V2)
round(c(mean(data$V1), sd(data$V1)), 1)
round(c(mean(data$V2), sd(data$V2)), 1)
summary(lm(V2 \sim V1, data = data))
# Generate multiple variables
cor_matrix <- matrix(</pre>
 c(
   1.0, 0.2, 0.4,
   0.2, 1.0, 0.3,
   0.4, 0.3, 1.0
 ),
 nrow = 3
)
data <- simulate_correlation(r = cor_matrix, names = c("y", "x1", "x2"))</pre>
summary(lm(y \sim x1, data = data))
# t-test ------
data \leftarrow simulate_ttest(n = 30, d = 0.3)
plot(data$V1, data$V0)
round(c(mean(data$V1), sd(data$V1)), 1)
diff(t.test(data$V1 ~ data$V0)$estimate)
summary(lm(V1 \sim V0, data = data))
summary(glm(V0 ~ V1, data = data, family = "binomial"))
# Difference ------
data <- simulate_difference(n = 30, d = 0.3)</pre>
plot(data$V1, data$V0)
round(c(mean(data$V1), sd(data$V1)), 1)
diff(t.test(data$V1 ~ data$V0)$estimate)
summary(lm(V1 \sim V0, data = data))
summary(glm(V0 ~ V1, data = data, family = "binomial"))
```

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# **Description**

Transforms priors information to actual distributions.

# Usage

```
simulate_prior(model, n = 1000, ...)
```

# Arguments

```
model A stanreg, stanfit, brmsfit, blavaan, or MCMCglmm object.

n Size of the simulated prior distributions.

... Currently not used.
```

#### See Also

unupdate() for directly sampling from the prior distribution (useful for complex priors and designs).

# **Examples**

```
library(bayestestR)
if (require("rstanarm")) {
  model <- suppressWarnings(
    stan_glm(mpg ~ wt + am, data = mtcars, chains = 1, refresh = 0)
  )
  simulate_prior(model)
}</pre>
```

simulate\_simpson

Simpson's paradox dataset simulation

# Description

Simpson's paradox, or the Yule-Simpson effect, is a phenomenon in probability and statistics, in which a trend appears in several different groups of data but disappears or reverses when these groups are combined.

```
simulate_simpson(
  n = 100,
  r = 0.5,
  groups = 3,
  difference = 1,
  group_prefix = "G_"
)
```

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# **Arguments**

n The number of observations for each group to be generated (minimum 4).

r A value or vector corresponding to the desired correlation coefficients.

groups Number of groups (groups can be participants, clusters, anything).

difference between groups.

group\_prefix The prefix of the group name (e.g., "G\_1", "G\_2", "G\_3", ...).

#### Value

A dataset.

# **Examples**

```
data <- simulate_simpson(n = 10, groups = 5, r = 0.5)
if (require("ggplot2")) {
   ggplot(data, aes(x = V1, y = V2)) +
    geom_point(aes(color = Group)) +
    geom_smooth(aes(color = Group), method = "lm") +
   geom_smooth(method = "lm")
}</pre>
```

spi

Shortest Probability Interval (SPI)

# **Description**

Compute the **Shortest Probability Interval (SPI)** of posterior distributions. The SPI is a more computationally stable HDI. The implementation is based on the algorithm from the **SPIn** package.

```
spi(x, ...)
## S3 method for class 'numeric'
spi(x, ci = 0.95, verbose = TRUE, ...)
## S3 method for class 'data.frame'
spi(x, ci = 0.95, rvar_col = NULL, verbose = TRUE, ...)
## S3 method for class 'stanreg'
spi(
    x,
    ci = 0.95,
    effects = c("fixed", "random", "all"),
```

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```
component = c("location", "all", "conditional", "smooth_terms", "sigma",
    "distributional", "auxiliary"),
parameters = NULL,
verbose = TRUE,
...
)

## S3 method for class 'brmsfit'

spi(
    x,
    ci = 0.95,
    effects = c("fixed", "random", "all"),
    component = c("conditional", "zi", "zero_inflated", "all"),
    parameters = NULL,
    verbose = TRUE,
    ...
)

## S3 method for class 'get_predicted'

spi(x, ci = 0.95, use_iterations = FALSE, verbose = TRUE, ...)
```

# **Arguments**

vector representing a posterior distribution, or a data frame of such vectors. Can also be a Bayesian model. bayestestR supports a wide range of models (see, for example, methods("hdi")) and not all of those are documented in the 'Usage' section, because methods for other classes mostly resemble the arguments of the .numeric or .data.framemethods.

... Currently not used.

ci Value or vector of probability of the (credible) interval - CI (between 0 and 1) to

be estimated. Default to .95 (95%).

verbose Toggle off warnings.

rvar\_col A single character - the name of an rvar column in the data frame to be pro-

cessed. See example in p\_direction().

effects Should results for fixed effects, random effects or both be returned? Only applies

to mixed models. May be abbreviated.

component Should results for all parameters, parameters for the conditional model or the

zero-inflated part of the model be returned? May be abbreviated. Only applies

to brms-models.

parameters Regular expression pattern that describes the parameters that should be returned.

Meta-parameters (like lp\_\_ or prior\_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to

select specific parameters for the output.

use\_iterations Logical, if TRUE and x is a get\_predicted object, (returned by insight::get\_predicted()),

the function is applied to the iterations instead of the predictions. This only applies to models that return iterations for predicted values (e.g., brmsfit models).

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#### **Details**

The SPI is an alternative method to the HDI (hdi()) to quantify uncertainty of (posterior) distributions. The SPI is said to be more stable than the HDI, because, the "HDI can be noisy (that is, have a high Monte Carlo error)" (Liu et al. 2015). Furthermore, the HDI is sensitive to additional assumptions, in particular assumptions related to the different estimation methods, which can make the HDI less accurate or reliable.

## Value

A data frame with following columns:

- Parameter The model parameter(s), if x is a model-object. If x is a vector, this column is missing.
- CI The probability of the credible interval.
- CI\_low, CI\_high The lower and upper credible interval limits for the parameters.

#### Note

The code to compute the SPI was adapted from the SPIn package, and slightly modified to be more robust for Stan models. Thus, credits go to Ying Liu for the original SPI algorithm and R implementation.

## References

Liu, Y., Gelman, A., & Zheng, T. (2015). Simulation-efficient shortest probability intervals. Statistics and Computing, 25(4), 809–819. https://doi.org/10.1007/s11222-015-9563-8

#### See Also

```
Other ci: bci(), ci(), eti(), hdi(), si()
```

```
library(bayestestR)

posterior <- rnorm(1000)
    spi(posterior)
    spi(posterior, ci = c(0.80, 0.89, 0.95))

df <- data.frame(replicate(4, rnorm(100)))
    spi(df)
    spi(df, ci = c(0.80, 0.89, 0.95))

library(rstanarm)
    model <- suppressWarnings(
        stan_glm(mpg ~ wt + gear, data = mtcars, chains = 2, iter = 200, refresh = 0)
    )
    spi(model)</pre>
```

weighted\_posteriors Generate posterior distributions weighted across models

# Description

Extract posterior samples of parameters, weighted across models. Weighting is done by comparing posterior model probabilities, via bayesfactor\_models().

```
weighted_posteriors(..., prior_odds = NULL, missing = 0, verbose = TRUE)
## S3 method for class 'data.frame'
weighted_posteriors(..., prior_odds = NULL, missing = 0, verbose = TRUE)
## S3 method for class 'stanreg'
weighted_posteriors(
  . . . ,
  prior_odds = NULL,
 missing = 0,
  verbose = TRUE,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL
)
## S3 method for class 'brmsfit'
weighted_posteriors(
  prior_odds = NULL,
 missing = 0,
 verbose = TRUE,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL
)
## S3 method for class 'blavaan'
weighted_posteriors(
  . . . ,
  prior_odds = NULL,
 missing = 0,
  verbose = TRUE,
  effects = c("fixed", "random", "all"),
  component = c("conditional", "zi", "zero_inflated", "all"),
  parameters = NULL
)
```

```
## S3 method for class 'BFBayesFactor'
weighted_posteriors(
    ...,
    prior_odds = NULL,
    missing = 0,
    verbose = TRUE,
    iterations = 4000
)
```

# **Arguments**

• • •	Fitted models (see details), all fit on the same data, or a single BFBayesFactor object.
prior_odds	Optional vector of prior odds for the models compared to the first model (or the denominator, for BFBayesFactor objects). For data.frames, this will be used as the basis of weighting.
missing	An optional numeric value to use if a model does not contain a parameter that appears in other models. Defaults to 0.
verbose	Toggle off warnings.
effects	Should results for fixed effects, random effects or both be returned? Only applies to mixed models. May be abbreviated.
component	Should results for all parameters, parameters for the conditional model or the zero-inflated part of the model be returned? May be abbreviated. Only applies to <b>brms</b> -models.
parameters	Regular expression pattern that describes the parameters that should be returned. Meta-parameters (like lp_ or prior_) are filtered by default, so only parameters that typically appear in the summary() are returned. Use parameters to select specific parameters for the output.

# **Details**

iterations

Note that across models some parameters might play different roles. For example, the parameter A plays a different role in the model Y ~ A + B (where it is a main effect) than it does in the model Y ~ A + B + A:B (where it is a simple effect). In many cases centering of predictors (mean subtracting for continuous variables, and effects coding via contr.sum or orthonormal coding via contr.equalprior\_pairs for factors) can reduce this issue. In any case you should be mindful of this issue.

For BayesFactor models, how many posterior samples to draw.

See bayesfactor\_models() details for more info on passed models.

Note that for BayesFactor models, posterior samples cannot be generated from intercept only models.

This function is similar in function to brms::posterior\_average.

# Value

A data frame with posterior distributions (weighted across models).

#### Note

For BayesFactor < 0.9.12-4.3, in some instances there might be some problems of duplicate columns of random effects in the resulting data frame.

#### References

- Clyde, M., Desimone, H., & Parmigiani, G. (1996). Prediction via orthogonalized model mixing. Journal of the American Statistical Association, 91(435), 1197-1208.
- Hinne, M., Gronau, Q. F., van den Bergh, D., and Wagenmakers, E. (2019, March 25). A conceptual introduction to Bayesian Model Averaging. doi:10.31234/osf.io/wgb64
- Rouder, J. N., Haaf, J. M., & Vandekerckhove, J. (2018). Bayesian inference for psychology, part IV: Parameter estimation and Bayes factors. Psychonomic bulletin & review, 25(1), 102-113.
- van den Bergh, D., Haaf, J. M., Ly, A., Rouder, J. N., & Wagenmakers, E. J. (2019). A cautionary note on estimating effect size.

#### See Also

bayesfactor\_inclusion() for Bayesian model averaging.

```
if (require("rstanarm") && require("see") && interactive()) {
 stan_m0 <- suppressWarnings(stan_glm(extra ~ 1,</pre>
    data = sleep,
    family = gaussian(),
    refresh = 0,
    diagnostic_file = file.path(tempdir(), "df0.csv")
 ))
 stan_m1 <- suppressWarnings(stan_glm(extra ~ group,</pre>
    data = sleep,
    family = gaussian(),
   refresh = 0,
   diagnostic_file = file.path(tempdir(), "df1.csv")
 ))
 res <- weighted_posteriors(stan_m0, stan_m1, verbose = FALSE)</pre>
 plot(eti(res))
}
## With BayesFactor
if (require("BayesFactor")) {
 extra_sleep <- ttestBF(formula = extra ~ group, data = sleep)</pre>
 wp <- weighted_posteriors(extra_sleep, verbose = FALSE)</pre>
 describe_posterior(extra_sleep, test = NULL, verbose = FALSE)
 # also considers the null
```

```
describe_posterior(wp$delta, test = NULL, verbose = FALSE)
## weighted prediction distributions via data.frames
if (require("rstanarm") && interactive()) {
 m0 <- suppressWarnings(stan_glm(</pre>
   mpg ~ 1,
   data = mtcars,
   family = gaussian(),
   diagnostic_file = file.path(tempdir(), "df0.csv"),
    refresh = 0
 ))
 m1 <- suppressWarnings(stan_glm(</pre>
   mpg ~ carb,
   data = mtcars,
   family = gaussian(),
   diagnostic_file = file.path(tempdir(), "df1.csv"),
    refresh = 0
 ))
 # Predictions:
 pred_m0 <- data.frame(posterior_predict(m0))</pre>
 pred_m1 <- data.frame(posterior_predict(m1))</pre>
 BFmods <- bayesfactor_models(m0, m1, verbose = FALSE)</pre>
 wp <- weighted_posteriors(</pre>
   pred_m0, pred_m1,
   prior_odds = as.numeric(BFmods)[2],
   verbose = FALSE
 # look at first 5 prediction intervals
 hdi(pred_m0[1:5])
 hdi(pred_m1[1:5])
 hdi(wp[1:5]) # between, but closer to pred_m1
}
```

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