Package 'mrbsizeR'

February 14, 2024

Type Package

Title Scale Space Multiresolution Analysis of Random Signals

Version 1.3

Date 2024-02-13

Maintainer Roman Flury <roman.flury@math.uzh.ch>

Description A method for the multiresolution analysis of spatial fields and images to capture scaledependent features.

mrbsizeR is based on scale space smoothing and uses differences of smooths at neighbouring scales for finding features on different scales.

To infer which of the captured features are credible, Bayesian analysis is used.

The scale space multiresolution analysis has three steps: (1) Bayesian signal reconstruction. (2) Using differences of smooths, scale-

dependent features of the reconstructed signal can be found.

(3) Posterior credibility analysis of the differences of smooths created.

The method has first been proposed by Holmstrom, Pasanen, Fur-

rer, Sain (2011) <DOI:10.1016/j.csda.2011.04.011> and extended in Flury, Ger-

ber, Schmid and Furrer (2021) <DOI:10.1016/j.spasta.2020.100483>.

License GPL-2

Depends R (>= 3.0.0), maps(>= 3.1.1)

Imports fields (>= 8.10), stats (>= 3.0.0), grDevices(>= 3.0.0), graphics(>= 3.0.0), methods(>= 3.0.0), Rcpp (>= 0.12.14)

LinkingTo Rcpp

RoxygenNote 7.2.3

Suggests knitr, rmarkdown, testthat

VignetteBuilder knitr

BugReports https://github.com/romanflury/mrbsizeR/issues

URL https://github.com/romanflury/mrbsizeR,

https://romanflury.github.io/mrbsizeR/

NeedsCompilation yes

CImap

Author Thimo Schuster [aut], Roman Flury [cre, aut], Leena Pasanen [ctb], Reinhard Furrer [ctb]

Repository CRAN

Date/Publication 2024-02-14 00:01:17 UTC

R topics documented:

CImap	2
dctMatrix	3
dftMatrix	4
eigenLaplace	5
eigenQsphere	6
fftshift	7
HPWmap	8
ifftshift	9
MinLambda	10
mrbsizeR	11
mrbsizeRgrid	13
mrbsizeRsphere	14
plot.CImapGrid	16
plot.CImapSphere	17
plot.HPWmapGrid	19
plot.HPWmapSphere	20
plot.minLambda	22
plot.smMeanGrid	23
plot.smMeanSphere	24
rmvtDCT	25
TaperingPlot	26
tridiag	27
turnmat	28
	20
	29

Index

```
CImap
```

Computation of simultaneous credible intervals.

Description

Simultaneous credible intervals for all differences of smooths at neighboring scales z_i are computed.

Usage

CImap(smoothVec, mm, nn, prob = 0.95)

dctMatrix

Arguments

smoothVec	Differences of smooths at neighboring scales.
mm	Number of rows of the original input object.
nn	Number of columns of the original input object.
prob	Credibility level for the posterior credibility analysis. By default prob = 0.95.

Details

CImap is an internal function of mrbsizeRgrid and is usually not used independently. The output can be analyzed with the plotting function plot.CImapGrid.

Value

An array with simultaneous credible intervals VmapCI and the dimensions of the original input object, mm and nn.

Examples

```
# Artificial sample data: 10 observations (5-by-2 object), 10 samples
set.seed(987)
sampleData <- matrix(stats::rnorm(100), nrow = 10)
sampleData [4:6, ] <- sampleData [4:6, ] + 5
# Calculation of the simultaneous credible intervals</pre>
```

```
CImap(smoothVec = sampleData , mm = 5, nn = 2, prob = 0.95)
```

dctMatrix

Create a n-by-n discrete cosine transform matrix.

Description

The discrete cosine transform (DCT) matrix for a given dimension n is calculated.

Usage

```
dctMatrix(n)
```

Arguments

n

Dimension for the DCT matrix.

Details

The function can be used for 1D- or 2D-DCT transforms of data.

- 1D: Let Q be a m-by-n matrix with some data. D is a m-by-m DCT matrix created by dctMatrix(m). Then D %*% Q returns the discrete cosine transform of the columns of Q. t(D) %*% Q returns the inverse DCT of the columns of Q. As D is orthogonal, solve(D) = t(D).
- 2D: Let Q be a m-by-n matrix with some data. D_m is a m-by-m DCT matrix created by dctMatrix(m), D_n a n-by-n DCT matrix created by dctMatrix(n). D_m %*% Q %*% t(D_n) computes the 2D-DCT of Q. The inverse 2D-DCT of Q can be computed via t(D_mm) %*% DCT_Q %*% D_n. D_m transforms along columns, D_n along rows. Since D is orthogonal, solve(D) = t(D).

It can be faster to use dctMatrix than using a direct transformation, especially when calculating several DCT's.

Value

The n-by-n DCT matrix.

Examples

D <- dctMatrix(5)</pre>

dftMatrix

Create a n-by-n discrete Fourier transform matrix.

Description

The discrete Fourier transform (DFT) matrix for a given dimension n is calculated.

Usage

dftMatrix(n)

Arguments

n

Dimension for the DFT matrix.

Details

The DFT matrix can be used for computing the discrete Fourier transform of a matrix or vector. dftMatrix(n) %*% testMatrix is the same as apply(testMatrix, MARGIN = 2, FUN = fft).

Value

The n-by-n DFT matrix.

eigenLaplace

Examples

```
set.seed(987)
testMatrix <- matrix(sample(1:10, size = 25, replace = TRUE), nrow = 5)
D <- dftMatrix(5)
# Discrete Fourier transform with matrix multiplication:
D %*% testMatrix
# Discrete Fourier transform with function fft:
apply(testMatrix, MARGIN = 2, FUN = fft)</pre>
```

eigenLaplace Generate eigenvalues of discrete Laplace matrix.

Description

The eigenvalues of a discrete Laplace matrix with dimension (mm, nn) are calculated.

Usage

```
eigenLaplace(mm, nn)
```

Arguments

mm	Number of rows of the discrete Laplace matrix.
nn	Number of columns of the discrete Laplace matrix.

Value

A row vector containing the eigenvalues of the discrete laplace matrix.

Examples

eigval <- eigenLaplace(5, 5)</pre>

eigenQsphere

Description

The eigenvalues of the precision matrix Q with dimension (mm, nn) and polar angle limits phimin, phimax are calculated.

Usage

```
eigenQsphere(phimin, phimax, mm, nn)
```

Arguments

phimin	Polar angle minimum.
phimax	Polar angle maximum.
mm	Number of rows of precision matrix Q.
nn	Number of columns of precision matrix Q.

Details

The corresponding function for data on a grid is eigenLaplace.

Value

A list containing 2 elements:

- eigval Row vector containing the eigenvalues of Q.
- eigvec Matrix containing the eigenvectors of Q as columns.

```
eig_out <- eigenQsphere(phimin = 180/10, phimax = 180 - 180/10, mm = 10, nn = 20)
```

fftshift

Description

fftshift is an R equivalent to the Matlab function fftshift applied on matrices. For more information about fftshift see the Matlab documentation.

Usage

```
fftshift(inputMatrix, dimension = -1)
```

Arguments

inputMatrix	Matrix to be swapped.
dimension	Which swap should be performed?
	• 1: swap halves along the rows.
	• 2: swap halves along the columns.

• -1: swap first quadrant with third and second quadrant with fourth.

Details

It is possible to swap the halves or the quadrants of the input matrix. Halves can be swapped along the rows (dimension = 1) or along the columns (dimension = 2). When swapping the quadrants, fftshift swaps the first quadrant with the third and the second quadrant with the fourth (dimension = -1).

Value

Swapped matrix.

```
set.seed(987)
sampleMat <- matrix(sample(1:10, size = 25, replace = TRUE), nrow = 5)
# Swap halves along the rows:
fftshift(sampleMat, dimension = 1)
# Swap halves along the columns:
fftshift(sampleMat, dimension = 2)
# Swap first quadrant with third and second quadrant with fourth:
fftshift(sampleMat, dimension = -1)</pre>
```

HPWmap

Description

Pointwise (PW) probabilities and highest pointwise (HPW) probabilities of all differences of smooths at neighboring scales are computed.

Usage

```
HPWmap(smoothVec, mm, nn, prob = 0.95)
```

Arguments

sis
sis

Details

HPWmap is an internal function of mrbsizeRgrid and is usually not used independently. The output can be analyzed with the plotting function plot.HPWmapGrid.

Value

List with two arrays:

- pw: Pointwise probabilities (VmapPW) including the dimensions of the original input image, mm and nn.
- hpw: Highest pointwise probabilities (VmapHPW) including the dimensions of the original input image, mm and nn.

Examples

```
# Artificial sample data: 10 observations (5-by-2 object), 10 samples
set.seed(987)
sampleData <- matrix(stats::rnorm(100), nrow = 10)
sampleData[4:6, ] <- sampleData[4:6, ] + 5</pre>
```

Calculation of the simultaneous credible intervals HPWmap(smoothVec = sampleData, mm = 5, nn = 2, prob = 0.95) ifftshift

Description

ifftshift is an R equivalent to the Matlab function ifftshift applied on matrices. For more information about ifftshift see the Matlab documentation.

Usage

```
ifftshift(inputMatrix, dimension = -1)
```

Arguments

inputMatrix	Matrix to be swapped.
dimension	Which swap should be performed?
	• 1: swap halves along the rows.
	• 2: swap halves along the columns.
	• -1: swap first quadrant with third and second quadrant with fourth.

Details

ifftshift is the inverse function to fftshift. For more information see the details of fftshift

Value

Swapped matrix.

```
set.seed(987)
sampleMat <- matrix(sample(1:10, size = 25, replace = TRUE), nrow = 5)
# Swap halves along the rows:
ifftshift(sampleMat, dimension = 1)
# Swap halves along the columns:
ifftshift(sampleMat, dimension = 2)
# Swap first quadrant with third and second quadrant with fourth:
ifftshift(sampleMat, dimension = -1)</pre>
```

MinLambda

Description

Numerical optimization of an objective function G is carried out to find appropriate signal-dependent smoothing levels (λ 's). This is easier than visual inspection via the signal-dependent tapering function in TaperingPlot.

Usage

MinLambda(Xmu, mm, nn, nGrid, nLambda = 2, lambda, sphere = FALSE)

Arguments

Xmu	Posterior mean of the input object as a vector.
mm	Number of rows of the original input object.
nn	Number of columns of the original input object.
nGrid	Size of grid where objective function is evaluated (nGrid-by-nGrid). This argument is ignorded if a sequence lambda is specified.
nLambda	Number of lambdas to minimize over. Possible arguments: 2 (default) or 3.
lambda	λ -sequence which is used for optimization. If nothing is provided, lambda <- 10^seq(-3, 10, len = nGrid) is used for data on a grid and lambda <- 10^seq(-6, 1, len = nGrid) is used for spherical data.
sphere	TRUE or FALSE: Is the input object defined on a sphere?

Details

As signal-dependent tapering functions are quiet irregular, it is hard to find appropriate smoothing values only by visual inspection of the tapering function plot. A more formal approach is the numerical optimization of an objective function.

Optimization can be carried out with 2 or 3 smoothing parameters. As the smoothing parameters 0 and ∞ are always added, this results in a mrbsizeR analysis with 4 or 5 smoothing parameters.

Sometimes, not all features of the input object can be extracted using the smoothing levels proposed by MinLambda. It might then be necessary to include additional smoothing levels.

plot.minLambda creates a plot of the objective function G on a grid. The minimum is indicated with a white point. The minimum values of the λ 's can be extracted from the output of MinLambda, see examples.

Value

A list with 3 objects:

G Value of objective function G.

lambda Evaluated smoothing parameters λ .

minind Index of minimal λ 's. lambda[minind] gives the minimal values.

mrbsizeR

Examples

mrbsizeR

mrbsizeR: Scale space multiresolution analysis in R.

Description

mrbsizeR contains a method for the scale space multiresolution analysis of spatial fields and images to capture scale-dependent features. The name is an abbreviation for MultiResolution Bayesian SIgnificant ZEro crossings of derivatives in **R** and the method combines the concept of statistical scale space analysis with a Bayesian SiZer method.

Details

The mrbsizeR analysis can be applied to data on a regular grid and to spherical data. For data on a grid, the scale space multiresolution analysis has three steps:

- 1. Bayesian signal reconstruction.
- 2. Using differences of smooths, scale-dependent features of the reconstructed signal are found.
- 3. Posterior credibility analysis of the differences of smooths created.

In a first step, Bayesian signal reconstruction is used to extract an underlying signal from a potentially noisy observation. Samples of the resulting posterior can be generated and used for the analysis. For finding features on different scales, differences of smooths at neighboring scales are used. This is an important distinction to other scale space methods (which usually use a wide range of smoothing levels without taking differences) and tries to separate the features into distinct scale categories more aggressively. After a successful extraction of the scale-different features, posterior credibility analysis is necessary to assess whether the features found are "really there" or if they are artifacts of random sampling.

For spherical data, no Bayesian signal reconstruction is implemented in mrbsizer. Data samples therefore need to be available beforehand. The analysis procedure can therefore be summarized in two steps:

- 1. Using differences of smooths, scale-dependent features of the reconstructed signal are found.
- 2. Posterior credibility analysis of the differences of smooths created.

This method has first been proposed by Holmstrom, Pasanen, Furrer, Sain (2011), see also http://cc.oulu.fi/~lpasanen/MRBSiZer/.

Major Functions

- TaperingPlot Graphical estimation of useful smoothing levels. Can be used signal-independent and signal-dependent.
- MinLambda Numerical estimation of useful smoothing levels. Takes the underlying signal into account. plot.minLambda can be used for plotting the result.
- rmvtDCT Creates samples on a regular grid from a multivariate t_{ν} -distribution using a discrete cosine transform (DCT).
- mrbsizeRgrid Interface of the mrbsizeR method for data on a regular grid. Differences of smooths at neighboring scales are created and posterior credibility analysis is conducted. The results can be visualized using plot.smMeanGrid,plot.HPWmapGrid and plot.CImapGrid.
- mrbsizeRsphere Interface of the mrbsizeR method for data on a sphere. Differences of smooths at neighboring scales are created and posterior credibility analysis is conducted. The results can be visualized using plot.smMeanSphere,plot.HPWmapSphere and plot.CImapSphere. For data on a sphere, no Bayesian signal reconstruction is implemented. Samples have to be provided instead.

Getting Started

The vignette for this package offers an extensive overview of the functionality and the usage of mrbsizeR.

References

- Holmstrom, L. and Pasanen, L. (2011). MRBSiZer. http://cc.oulu.fi/~lpasanen/MRBSiZer/. Accessed: 2017-03-04.
- Holmstrom, L., Pasanen, L., Furrer, R., and Sain, S. R. (2011). Scale space multiresolution analysis of random signals. Computational Statistics and Data Analysis, 55, 2840-2855.
- Holmstrom, L. and Pasanen, L. (2016). Statistical scale space methods. International Statistical Review. <DOI:10.1111/insr.12155>.

DISCLAIMER: The author can not guarantee the correctness of any function or program in this package.

```
lambdaSmoother = c(1, 1000), prob = 0.95)
# Posterior mean of the differences of smooths
plot(x = mrbOut$smMean, turn_out = TRUE)
# Credibility analysis using simultaneous credible intervals
plot(x = mrbOut$ciout, turn_out = TRUE)
```

mrbsizeRgrid

Multiresolution analysis of random signals.

Description

mrbsizeRgrid is the interface of the scale space multiresolution method for data on a regular grid. Here, the differences of smooths as well as the posterior credibility analysis are computed. The output can be analyzed with the plotting functions plot.smMeanGrid, plot.CImapGrid and plot.HPWmapGrid.

Usage

```
mrbsizeRgrid(
   posteriorFile,
   mm,
   nn,
   lambdaSmoother,
   prob = 0.95,
   smoothOut = FALSE
)
```

Arguments

posteriorFile	Matrix with posterior samples as column vectors.
mm	Number of rows of the original object.
nn	Number of columns of the original object.
lambdaSmoother	Vector consisting of the smoothing levels to be used.
prob	Credibility level for the posterior credibility analysis.
smoothOut	Should the differences of smooths at neighboring scales be returned as output (FALSE by default)?

Details

mrbsizeRgrid conducts two steps of the scale space multiresolution analysis:

1. Extraction of scale-dependent features from the reconstructed signal. This is done by smoothing at different smoothing levels and taking the difference of smooths at neighboring scales.

2. Posterior credibility analysis of the differences of smooths created. Three different methods are applied: Pointwise probabilities (see HPWmap), highest pointwise probabilities (see HPWmap) and simultaneous credible intervals (see CImap).

The signal can be reconstructed using the build-in multivariate t-distribution sampling rmvtDCT. It is also possible to provide samples generated with other methods, see the parameter posteriorFile and the examples.

For further information and examples, see the vignette.

Value

A list containing the following sublists:

smMean Posterior mean of all differences of smooths created.

hpout Pointwise (PW) and highest pointwise (HPW) probabilities of all differences of smooths created.

ciout Simultaneous credible intervals (CI) of all differences of smooths created.

smoothSamples Samples of differences of smooths at neighboring scales, as column vectors.

Examples

mrbsizeRsphere Multiresolution analysis of random signals for spherical data.

Description

mrbsizeRSphere is the interface of the scale space multiresolution method for spherical data. Here, the differences of smooths as well as the posterior credibility analysis are computed. The output can be analyzed with the plotting functions plot.smMeanSphere, plot.CImapSphere and plot.HPWmapSphere.

mrbsizeRsphere

Usage

```
mrbsizeRsphere(
   posteriorFile,
   mm,
   nn,
   lambdaSmoother,
   prob = 0.95,
   smoothOut = FALSE
)
```

Arguments

posteriorFile	Matrix with posterior samples as column vectors.
mm	Number of rows of the original object.
nn	Number of columns of the original object.
lambdaSmoother	Vector consisting of the smoothing levels to be used.
prob	Credibility level for the posterior credibility analysis.
smoothOut	Should the differences of smooths at neighboring scales be returned as output (FALSE by default)?

Details

In contrast to mrbsizeRgrid, mrbsizeRsphere does not conduct Bayesian signal reconstruction via sampling from a posterior distribution. Samples of the posterior distribution have to be provided instead.

For further information and examples, see mrbsizeRgrid and the vignette.

Value

A list containing the following sublists:

smMean Posterior mean of all differences of smooths created.

hpout Pointwise (PW) and highest pointwise (HPW) probabilities of all differences of smooths created.

ciout Simultaneous credible intervals (CI) of all differences of smooths created.

smoothSamples Samples of differences of smooths at neighboring scales, as column vectors.

plot.CImapGrid

Description

Maps with simultaneous credible intervals for all differences of smooths at neighboring scales z_i are plotted.

Usage

```
## S3 method for class 'CImapGrid'
plot(
    x,
    color = c("firebrick1", "gainsboro", "dodgerblue3"),
    turnOut = TRUE,
    title,
    aspRatio = 1,
    ...
)
```

Arguments

х	List containing the simultaneous credible intervals for all differences of smooths.
color	Vector of length 3 containing the colors to be used in the credibility maps. The first color represents the credibly negative pixels, the second color the pixels that are not credibly different from zero and the third color the credibly positive pixels.
turnOut	Logical. Should the output images be turned 90 degrees counter-clockwise?
title	Vector containing one string per plot. The required number of titles is equal to length(mrbOut\$ciout). If no title is passed, defaults are used.
aspRatio	Adjust the aspect ratio of the plots. The default aspRatio = 1 produces square plots.
	Further graphical parameters can be passed.

Details

The default colors of the maps have the following meaning:

- Blue: Credibly positive pixels.
- Red: Credibly negative pixels.
- Grey: Pixels that are not credibly different from zero.

x corresponds to the ciout-part of the output of mrbsizeRgrid.

Value

Plots of simultaneous credible intervals for all differences of smooths are created.

plot.CImapSphere

Examples

plot.CImapSphere *Plotting of simultaneous credible intervals on a sphere.*

Description

Maps with simultaneous credible intervals for all differences of smooths at neighboring scales z_i are plotted. Continental lines are added.

Usage

```
## S3 method for class 'CImapSphere'
plot(
    x,
    lon,
    lat,
    color = c("firebrick1", "gainsboro", "dodgerblue3"),
    turnOut = FALSE,
    title,
    ...
)
```

Arguments

x	List containing the simultaneous credible intervals of all differences of smooths.
lon	Vector containing the longitudes of the data points.
lat	Vector containing the latitudes of the data points.

color	Vector of length 3 containing the colors to be used in the credibility maps. The first color represents the credibly negative pixels, the second color the pixels that are not credibly different from zero and the third color the credibly positive pixels.
turnOut	Logical. Should the output images be turned 90 degrees counter-clockwise?
title	Vector containing one string per plot. The required number of titles is equal to length(mrbOut\$ciout). If no title is passed, defaults are used.
	Further graphical parameters can be passed.

Details

The default colors of the maps have the following meaning:

- Blue: Credibly positive pixels.
- Red: Credibly negative pixels.
- Grey: Pixels that are not credibly different from zero.

x corresponds to the ciout-part of the output of mrbsizeRsphere.

Value

Plots of simultaneous credible intervals for all differences of smooths are created.

plot.HPWmapGrid

Description

Maps with pointwise (PW) probabilities and/or highest pointwise (HPW) probabilities of all differences of smooths at neighboring scales are plotted.

Usage

```
## S3 method for class 'HPWmapGrid'
plot(
    x,
    plotWhich = "Both",
    color = c("firebrick1", "gainsboro", "dodgerblue3"),
    turnOut = TRUE,
    title,
    aspRatio = 1,
    ...
)
```

Arguments

x	List containing the pointwise (PW) and highest pointwise (HPW) probabilities of all differences of smooths.
plotWhich	Which probabilities shall be plotted? HPW, PW or Both?
color	Vector of length 3 containing the colors to be used in the credibility maps. The first color represents the credibly negative pixels, the second color the pixels that are not credibly different from zero and the third color the credibly positive pixels.
turnOut	Logical. Should the output images be turned 90 degrees counter-clockwise?
title	Vector containing one string per plot. The required number of titles is equal to length(mrbOut\$hpout). If no title is passed, defaults are used.
aspRatio	Adjust the aspect ratio of the plots. The default aspRatio = 1 produces square plots.
	Further graphical parameters can be passed.

Details

The default colors of the maps have the following meaning:

- Blue: Credibly positive pixels.
- Red: Credibly negative pixels.
- Grey: Pixels that are not credibly different from zero.

x corresponds to the hpout-part of the output of mrbsizeRgrid.

Value

Plots of pointwise and/or highest pointwise probabilities for all differences of smooths are created.

Examples

```
# Artificial sample data
set.seed(987)
sampleData <- matrix(stats::rnorm(100), nrow = 10)</pre>
sampleData[4:6, 6:8] <- sampleData[4:6, 6:8] + 5</pre>
# Generate samples from multivariate t-distribution
tSamp <- rmvtDCT(object = sampleData, lambda = 0.2, sigma = 6, nu0 = 15,
                   ns = 1000)
# mrbsizeRgrid analysis
mrbOut <- mrbsizeRgrid(posteriorFile = tSamp$sample, mm = 10, nn = 10,</pre>
                       lambdaSmoother = c(1, 1000), prob = 0.95)
# Posterior mean of the differences of smooths
plot(x = mrbOut$smMean, turnOut = TRUE)
# Credibility analysis using pointwise (PW) maps
plot(x = mrbOut$hpout, plotWhich = "PW", turnOut = TRUE)
# Credibility analysis using highest pointwise probability (HPW) maps
plot(x = mrbOut$hpout, plotWhich = "HPW", turnOut = TRUE)
```

plot.HPWmapSphere Plotting of pointwise and highest pointwise probabilities on a sphere.

Description

Maps with pointwise (PW) probabilities and/or highest pointwise (HPW) probabilities of all differences of smooths at neighboring scales are plotted. Continental lines are added.

Usage

```
## S3 method for class 'HPWmapSphere'
plot(
    x,
    lon,
    lat,
    plotWhich = "Both",
    color = c("firebrick1", "gainsboro", "dodgerblue3"),
    turnOut = FALSE,
    title,
    ...
)
```

Arguments

x	List containing the pointwise (PW) and highest pointwise (HPW) probabilities of all differences of smooths.
lon	Vector containing the longitudes of the data points.
lat	Vector containing the latitudes of the data points.
plotWhich	Which probabilities shall be plotted? HPW, PW or Both?
color	Vector of length 3 containing the colors to be used in the credibility maps. The first color represents the credibly negative pixels, the second color the pixels that are not credibly different from zero and the third color the credibly positive pixels.
turnOut	Logical. Should the output images be turned 90 degrees counter-clockwise?
title	Vector containing one string per plot. The required number of titles is equal to length(mrbOut\$hpout). If no title is passed, defaults are used.
	Further graphical parameters can be passed.

Details

The default colors of the maps have the following meaning:

- Blue: Credibly positive pixels.
- Red: Credibly negative pixels.
- Grey: Pixels that are not credibly different from zero.

x corresponds to the hpout-part of the output of mrbsizeRsphere.

Value

Plots of pointwise and/or highest pointwise probabilities for all differences of smooths are created.

```
# Credibility analysis using highest pointwise probability (HPW) maps
plot(x = mrbOut$hpout, lon = lon, lat = lat, plotWhich = "HPW")
```

plot.minLambda	Plot of objective function for finding appropriate smoothing parame-
	ters.

Description

The objective function G is plotted on a grid. The minimum is indicated with a white point.

Usage

```
## S3 method for class 'minLambda'
plot(x, ...)
```

Arguments

х	Output of function MinLambda.
	Further graphical parameters can be passed.

Details

When minimizing over 2 λ 's, one plot is generated: (λ_2 vs λ_3). With 3 λ 's, 3 plots are generated: λ_2 vs. λ_3 , λ_2 vs. λ_4 and λ_3 vs. λ_4 .

Value

Plot of G on a grid.

Examples

```
set.seed(987)
sampleData <- matrix(stats::rnorm(100), nrow = 10)
sampleData[4:6, 6:8] <- sampleData[4:6, 6:8] + 5</pre>
```

```
# Plot of the objective function
plot(x = minLamOut)
```

22

plot.smMeanGrid

Description

Scale-dependent features are plotted using differences of smooths at neighboring scales. The features are summarized by their posterior mean.

Usage

```
## S3 method for class 'smMeanGrid'
plot(
    x,
    color.pallet = fields::tim.colors(),
    turnOut = TRUE,
    title,
    aspRatio = 1,
    ...
)
```

Arguments

х	List containing the posterior mean of all differences of smooths.
color.pallet	The color pallet to be used for plotting scale-dependent features.
turnOut	Logical. Should the output images be turned 90 degrees counter-clockwise?
title	Vector containing one string per plot. The required number of titles is equal to length(mrbOut\$smMean). If no title is passed, defaults are used.
aspRatio	Adjust the aspect ratio of the plots. The default aspRatio = 1 produces square plots.
	Further graphical parameters can be passed.

Details

x corresponds to the smmean-part of the output of mrbsizeRgrid.

Value

Plots of the differences of smooths are created.

```
# Artificial sample data
set.seed(987)
sampleData <- matrix(stats::rnorm(100), nrow = 10)
sampleData[4:6, 6:8] <- sampleData[4:6, 6:8] + 5</pre>
```

plot.smMeanSphere *Plotting of scale-dependent features on a sphere.*

Description

Scale-dependent features are plotted using differences of smooths at neighboring scales. The features are summarized by their posterior mean. Continental lines are added to the plots.

Usage

```
## S3 method for class 'smMeanSphere'
plot(
    x,
    lon,
    lat,
    color.pallet = fields::tim.colors(),
    turnOut = TRUE,
    title,
    ...
)
```

Arguments

х	List containing the posterior mean of all differences of smooths.
lon	Vector containing the longitudes of the data points.
lat	Vector containing the latitudes of the data points.
color.pallet	The color pallet to be used for plotting scale-dependent features.
turnOut	Logical. Should the output images be turned 90 degrees counter-clockwise?
title	Vector containing one string per plot. The required number of titles is equal to length(mrbOut\$smMean). If no title is passed, defaults are used.
	Further graphical parameters can be passed.

Details

x corresponds to the smmean-part of the output of mrbsizeRsphere.

rmvtDCT

Value

Plots of the differences of smooths are created.

Examples

rmvtDCT

Sampling from marginal posterior multivariate t-distribution.

Description

Samples from a marginal posterior multivariate t-distribution with normal-inverse-chi-squared-prior are generated.

Usage

rmvtDCT(object, lambda, sigma, nu0, ns)

Arguments

object	Observed object, as matrix.
lambda	Scaling parameter (λ) of the normal-inverse-chi-squared-prior.
sigma	Square root of the σ_0^2 parameter of the normal-inverse-chi-squared-prior.
nu0	Degrees of freedom (ν_0) of the normal-inverse-chi-square-prior.
ns	Number of samples that should be generated.

Details

An eigenvalue decomposition is used for sampling. To speed up computations, a 2D discrete cosine transform (DCT) has been implemented, see dctMatrix. The output is a list containing

1. Samples of the marginal posterior of the input as column vectors.

2. The mean of the marginal posterior of the input as a vector.

Value

A list containing the following elements:

sample Samples of the marginal posterior of the input.

mu Mean of the marginal posterior of the input.

Examples

TaperingPlot

Plot of tapering functions.

Description

Tapering functions corresponding to the smoothing levels in lambdaSmoother are drawn. This plot helps to assess if the chosen smoothing levels are appropriate.

Usage

```
TaperingPlot(lambdaSmoother, mm, nn, Xmu, returnseq = FALSE, ...)
```

Arguments

lambdaSmoother	Vector consisting of the smoothing levels to be used.
mm	Number of rows of the original input object.
nn	Number of columns of the original input object.
Xmu	If availabe, posterior mean of the input object.
returnseq	instead of plotting return the tapering sequences.
	Further graphical parameters can be passed.

Details

The tapering functions of the smoothing levels chosen should be generally approximately disjoint. This will produce features which are somewhat orthogonal. With orthogonal features, it is likely that each difference of smooths corresponds to a different pattern in the input image.

Sometimes, not all patterns of the input image can be extracted using smoothing levels whose tapering functions are disjoint. It might then be necessary to include additional smoothing levels, and the disjointedness might not be satisfied anymore. The selection of appropriate smoothing

26

tridiag

levels with this method therefore requires some user interaction. Still, choosing disjoint tapering functions for finding appropriate smoothing levels is a good starting point.

Better results could be obtained if the structure of the posterior mean of the input is also taken into account. If the posterior mean is available, it can be added with the argument Xmu and moving averages of the absolute values of the signal-dependent tapering functions are drawn. MinLambda offers a more formal approach of optimizing the disjointedness of the tapering functions and can help finding appropriate smoothing levels when the input signal is taken into account.

Value

Plots of the tapering functions for all differences of smooths at neighboring scales are created.

Examples

```
# Signal-independent tapering function plot for a 30-by-10 object with
# the smoothing parameter sequence [0, 1, 10, 1000, inf]:
TaperingPlot(lambdaSmoother = c(1, 10, 1000), mm = 30, nn = 10)
# Signal-dependent tapering function plot for a 30-by-10 object with
# the smoothing parameter sequence [0, 1, 10, 1000, inf]:
set.seed(987)
xmuExample <- c(stats::rnorm(300))
TaperingPlot(lambdaSmoother = c(1, 10, 1000), mm = 30, nn = 10,
Xmu = xmuExample)
```

tridiag

Generate a tridiagonal matrix.

Description

Generate a tridiagonal matrix with upperDiag as superdiagonal, lowerDiag as subdiagonal and mainDiag as diagonal.

Usage

tridiag(mainDiag, upperDiag, lowerDiag)

Arguments

mainDiag	Diagonal of tridiagonal matrix.
upperDiag	Superdiagonal of tridiagonal matrix. Must have length length(mainDiag) - 1.
lowerDiag	Subdiagonal of tridiagonal matrix. Must have length length(mainDiag) - 1.

turnmat

Value

Tridiagonal matrix.

Examples

```
set.seed(987)
mainDiag <- sample(100:110, size = 6, replace = TRUE)
upperDiag <- sample(10:20, size = 5, replace = TRUE)
lowerDiag <- sample(1:10, size = 5, replace = TRUE)</pre>
```

tridiag(mainDiag, upperDiag, lowerDiag)

turnmat

Turn matrix 90 degrees counter-clockwise.

Description

Help function to turn matrix 90 degrees counter-clockwise. turnmat is used as an internal function in some of the plotting functions. Depending on how the data is stored, it can be necessary to turn the matrices 90 degrees counter-clockwise for being able to plot them correctly.

Usage

turnmat(x)

Arguments

x Matrix to be turned.

Value

Matrix x, turned by 90 degrees counter-clockwise.

Examples

```
set.seed(987)
sampleMat <- matrix(stats::rnorm(100), nrow = 10)
sampleMatTurn <- turnmat(x = sampleMat)</pre>
```

28

Index

CImap, 2, 14 dctMatrix, 3, 25 dftMatrix,4 eigenLaplace, 5, 6 eigenQsphere, 6fftshift, 7, 9 HPWmap, 8, 14 ifftshift,9 MinLambda, 10, 12, 22, 27 mrbsizeR, 11 mrbsizeRgrid, 3, 8, 12, 13, 15, 16, 19, 23 mrbsizeRsphere, 12, 14, 18, 21, 24 plot.CImapGrid, *3*, *12*, *13*, 16 plot.CImapSphere, *12*, *14*, 17 plot.HPWmapGrid, 8, 12, 13, 19 plot.HPWmapSphere, 12, 14, 20 plot.minLambda, *10*, *12*, 22 plot.smMeanGrid, *12*, *13*, 23 plot.smMeanSphere, 12, 14, 24 rmvtDCT, *12*, *14*, 25 TaperingPlot, *10*, *12*, 26 tridiag, 27

turnmat, 28